

1 **Title:** Spatial and Temporal Changes in Fishing Effort and Habitat Use

2 **Alternative title 1:** Mapping long-term fishing effort and seabed habitats

3 **Alternative title 2:** Decadal Changes in Spatial and Temporal Fishing Effort and

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16 **Suggested running title:** Pot-fishing effort and habitat use

17

18 **Abstract**

19 Habitat and fisheries usage data are key components for ecosystem based fisheries
20 management (EBFM). Significant gaps in knowledge remain for fisheries–habitat
21 interactions, particularly in inshore fisheries where vessels are <12m. Here we show
22 changes in inshore fishing effort distribution (<12m) and habitat use over the decade
23 2004-2013.

24 Sightings data of fishing vessel activity recorded by the Northumberland Inshore
25 Fishery and Conservation Authority (NIFCA) were combined with landings data to
26 estimate and map pot-fishing activity between 2004 and 2013. Spatial temporal
27 changes were investigated using Monte Carlo simulation of randomly sampled
28 fishing effort maps. High resolution (1m) broadscale (EUNIS level 3) predictive
29 habitat maps of the Coquet to St Marys' Marine Conservation Zone (CQSM MCZ)
30 were used to investigate spatial temporal changes in fishers' habitat selection using
31 compositional analysis.

32 Fishing effort in Northumberland increased between 2004 and 2013 (233,642-
33 354,193 pots.year⁻¹). Fishing effort distribution differed between individual years,
34 decreasing over large areas between 2004-2007, followed by increases, especially
35 inshore, between 2008-2013. Fishers in the CQSM MCZ showed a preference for
36 rocky habitats over sediment habitats. Habitat preference did not vary between years
37 although all habitats experienced increasing fishing pressure. Spatial temporal
38 changes in fishing effort and habitat use were discussed in relation to EBFM.

39 **Key words:** Baited traps, ecosystem based fisheries management, fishing effort
40 distribution, fisheries-habitat interactions, potting, spatio-temporal analysis.

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64 **1. Introduction**

65 Fishing provides an important socio-economic function in many parts of the world as
66 a source of food and income (Pauly *et al.*, 2002; Kaiser, 2014). The traditional model
67 of fisheries management focusses on single species bio-economic modelling,
68 although this method is increasingly perceived as incomplete (Caddy and Cochrane,
69 2001; Hilborn and Ovando, 2014). Habitat quality and health have now been
70 recognised as being integral to an ecosystem based approach to fisheries
71 management (EBFM) (Pikitch *et al.*, 2004; Armstrong and Falk-Petersen, 2008;
72 Howarth *et al.*, 2011; Salomidi *et al.*, 2012). Knowledge of fisheries effort distribution
73 and marine habitat usage is needed (Stelzenmüller *et al.*, 2008; Eno *et al.*, 2013;
74 Kaiser, 2014) in order to minimize the risk of irreversible changes to species
75 assemblages and ecosystem processes as part of EBFM (Pikitch *et al.*, 2004; Parnell
76 *et al.*, 2010).

77 Seabed habitats and their associated communities are determined by their ambient
78 biotic and abiotic conditions (Dayton, 1985; McGowan *et al.*, 1998; Shears and
79 Babcock, 2002; Connor *et al.*, 2004; Smale *et al.*, 2011). In addition to natural
80 environmental conditions, the physical interaction of fishing gears on the seafloor
81 may exert further pressure on benthic communities (Lambert *et al.*, 2011; Nielsen *et al.*,
82 2013). Vulnerability of habitats to fishing impacts will be determined by the
83 intensity, frequency and extent of natural disturbance to which the habitat and its
84 associated species are subject to (Kaiser *et al.*, 2006; Kaiser, 2014). For example, in
85 high-energy environments, fishing disturbances may have negligible effects when
86 compared to natural disturbance (Kulbicki *et al.*, 2007; Sciberras *et al.*, 2013). In
87 many cases, mobile fishing gears adversely affect the marine environment (Kaiser *et al.*,
88 1996; MacDonald *et al.*, 1996; Collie *et al.*, 1997; Collie *et al.*, 2000a; Collie *et al.*,
89 2000b; Kaiser *et al.*, 2006; Lambert *et al.*, 2011). Static fishing gears have been

90 widely assumed to be relatively benign (Eno *et al.*, 2001; Lewis *et al.*, 2009; Shester
91 and Micheli, 2011; Coleman *et al.*, 2013) yet there is limited evidence to support this
92 (Shester and Micheli, 2011) even though these fisheries are substantial; UK landings
93 were 86,600 tonnes and worth £173 million in 2014 (MMO, 2015). High-value
94 species such as lobster and crab constitute 41% of the landings and are primarily
95 caught inshore using pots or traps (MMO, 2015). The need for information on
96 impacts of these fisheries in UK designated conservation areas (European Marine
97 Sites [EMSs] and Marine Conservation Zones [MCZs]) has become increasingly
98 urgent for inshore static-gear fishing (MMO, 2016). Understanding effects of static
99 fishing gears on the marine environment requires an understanding of the
100 distribution, frequency, intensity and fisheries-habitat interactions (Pedersen *et al.*,
101 2009; Parnell *et al.*, 2010; Eno *et al.*, 2013; Caveen *et al.*, 2014; Kaiser, 2014).

102 To date, research has predominately focussed on mapping mobile gear fishing
103 activity using VMS and overlaying this information on existing broadscale habitat
104 datasets (Nilsson and Ziegler, 2007; Stelzenmüller *et al.*, 2008). However, a primary
105 limitation of VMS data is that it is only recorded for large vessels (>12m). Static-gear
106 fishing fleets, largely operate inshore and are composed of small vessels (<12m)
107 which do not have VMS equipment (Breen *et al.*, 2014). Alternative approaches to
108 mapping small vessels fishing activity (<12m), such as surveillance methods, have
109 successfully described distribution and intensity of various static fishing gears,
110 however, only over a single time period (Breen *et al.*, 2014; Turner *et al.*, 2015). This
111 does not account for changing use of habitats by fishers. Spatial fishing patterns
112 have been shown to vary over time (Kaiser *et al.*, 2002; Nilsson and Ziegler, 2007),
113 the availability of target species, gear and fishers' territorial behaviour being
114 important drivers (Acheson, 1975; Rijnsdorp *et al.*, 2001; Turner *et al.*, 2012). These
115 inter-annual variations in fishing activity may make short-term studies inadequate

116 (Lynch, 2014); spatio-temporal variability must be better understood to inform
117 appropriate management (Parnell *et al.*, 2010). Some temporal trends for large
118 vessels (>18m) over broadscale marine landscapes (Connor *et al.*, 2006) at 2x2
119 nautical mile (NM) resolution (Stelzenmüller *et al.*, 2008) have been described, but
120 finer resolution fishing activity has been repeatedly highlighted as a priority for future
121 research (Breen *et al.*, 2014; Campbell *et al.*, 2014), particularly for smaller vessels
122 (Caveen *et al.*, 2014; Brehme *et al.*, 2015).

123 Here, spatio-temporal changes in inshore static-gear fishing effort and habitat use
124 were investigated for the first time. The Northumberland fishery was used as a case
125 study for the assessment of other inshore fisheries due to the rich data available.
126 Northumberland's fishery (Fig 2) is mixed (Garside *et al.*, 2003), vessels largely
127 operate close to shore; approximately 90% of fishing effort is estimated to occur
128 within the 6NM limit (Turner, 2010) and is primarily composed of <10m fishing
129 vessels ($70 \pm 9\%$ between 2003 and 2014, Table 3). The majority of Northumberland
130 fishers target crustaceans, European lobster (*Homarus gammarus*), velvet crab
131 (*Necora puber*) and edible crab (*Cancer pagurus*), using baited pots (or traps). These
132 shellfish species use habitats differently from each other; their distributions,
133 movements and abundances are influenced by habitat type, quality and location
134 (Galparsoro *et al.*, 2009; Geraldi *et al.*, 2009; Skerritt *et al.*, 2015). Lobster (*Homarus*
135 *gammarus*) and velvet crab (*Necora puber*) are found predominantly on shallow
136 rocky ground (Wilson, 2008; Galparsoro *et al.*, 2009). The edible crab (*Cancer*
137 *pagurus*) is found in all habitat types but evidence suggests preferences for coarse
138 sediment and offshore muddy sand (Neal and Wilson, 2008). Thus fishers are likely
139 to select by habitat when targeting different shellfish species. Fishing with mobile
140 gear may vary inter-annually in both extent and habitats selected (Jennings *et al.*,
141 2012; Diesing *et al.*, 2013), but there have evidently been no comparable studies of

142 fishing with static potting gear. These may differ, for example, due to fishers'
143 territorial behaviours (Turner *et al.*, 2012).

144 The aim of this research was to investigate spatio-temporal changes in pot fishing
145 effort and habitat use in Northumberland coastal waters between 2004 and 2014.
146 This was achieved using routine patrol vessel sightings in combination with high
147 resolution habitat maps, providing a case study for the assessment of other inshore
148 fisheries. The scale needed for management of fisheries–habitat interactions were
149 also explored.

150 **2. Methods**

151 **2.1. Fishing activity**

152 Sightings data of fishing vessel activity recorded by the Northumberland Inshore
153 Fisheries Conservation Authority (NIFCA) on routine patrols were combined with
154 landings data to estimate and map fishing activity in the NIFCA district. This method
155 was based on Turner *et al.* (2015) and adapted for this research (Fig 1).

156 Fishing vessel sightings were recorded during routine NIFCA patrols between 2004
157 and 2013. Vessel name, registration, home port, geographic position and observed
158 activity were recorded. Sightings of potting vessels targeting crab and lobster in
159 2004–2013 were mapped as point data using ArcView GIS version 10.2 (ESRI,
160 2014) (Table 1). Sightings data provide strong confidence of association with actual
161 fishing activity because of the direct recording by the NIFCA officers of activity such
162 as shooting, hauling or attendance of gear by a fishing vessel. In order to standardise
163 sightings across years, all years' sightings data were randomly reduced to the
164 minimum number of patrol days (n=71 in 2009) (Table 1).

165 Frequency and location of fishing vessel sightings were influenced by the timing and
166 route of NIFCA patrols (Breen *et al.*, 2014; Turner *et al.*, 2015). Thus, sightings were
167 adjusted for patrol effort (Turner *et al.*, 2015), using patrol routes to weight the

168 probability of vessel sightings; heavily patrolled areas were negatively weighted and
169 lightly patrolled areas were positively weighted.

170 Due to low numbers of vessel sightings in some years, caused by the small number
171 of fishing vessels operating from some ports and the limited number of routine
172 patrols, sightings data were pooled in 2-year groupings (2004-2005; 2006-2007;
173 2008-2009; 2010-2011 and 2012-2013).

174 The pooled adjusted vessel sightings point data were transformed to a continuous
175 surface using a non-parametric quadratic kernel density estimation (KDE) method
176 (cell size 100x100m) in ESRI ArcGIS 10.2 (Silverman, 1986). A normal distribution
177 approximation bandwidth estimation method (Silverman, 1986) was chosen as the
178 density data was unimodal, fairly symmetric and did not have large tails (Wand and
179 Jones, 1995; Kie *et al.*, 2010). Highly clustered data can result in an exaggerated
180 bandwidth, over-smoothing the data and creating inaccurate utilization areas (Kie *et*
181 *al.*, 2010). By reducing this bandwidth to a fixed proportion of 0.8 over-smoothing
182 was reduced (Bertrand *et al.*, 1996; Kie and Boroski, 1996; Kie *et al.*, 2002; Kie *et al.*,
183 2010).

184 **2.2. Distribution of potting density**

185 Percentage volume contours (PVCs) delineate the smallest area accounting for a
186 specific proportion of the probability density distribution. These were created from the
187 potting activity KDEs using the 'Isopleth' tool in Geospatial Modelling Environment
188 (GME) software (St. Martin and Hall-Arber, 2008; Beyer, 2012). PVC polygons of 50,
189 60, 70, 80, 90 and 95% were created, uploaded into ArcGIS 10.2, and area
190 calculated (Turner *et al.*, 2015).

191 The numbers of pots worked per month over the period 2001-2014 in the
192 Northumberland district were provided by the NIFCA. Annual fishing effort (f ,
193 pots.year⁻¹) was calculated:

194 Eqn 1: $Mean\ Annual\ f = \frac{\Sigma\ pots.month^{-1}}{n}$

195 Where n is the number of years. For years 2006-2009 fishing effort data were
196 missing for vessels 10-12m. Total numbers of pots deployed between 2006 and 2009
197 were estimated by averaging the proportion of pots fished per year by 10-12m
198 vessels for years 2004-2005 and 2010-2014. The mean proportion of fished pots by
199 10-12m vessels was added to the available data for years 2006-2009. Average
200 proportion of pots fished by 10-12m vessels was $14.3 \pm 5.8\%$.

201 To estimate annual potting density, 50, 60, 70, 80, 90 and 95% of the mean annual
202 fishing effort was calculated and apportioned to the corresponding PVC polygon
203 (Turner *et al.*, 2015); for example, 50% of annual fishing effort was allocated to the
204 50% PVC with pot density calculated as number of pots.km⁻².year⁻¹.

205 **2.3. Confidence assessment**

206 Some areas were infrequently or never patrolled and therefore have uncertain or
207 unknown fishing activity intensity and distribution (Breen *et al.*, 2014). A confidence
208 assessment was made based on the frequency of patrol tracks contained within each
209 3NM² grid cell between 2004 and 2013 (Table 2).

210 Of the patrols within each 3NM² grid cell, 63.3% of the NIFCA district was mapped
211 with moderate or high confidence (Fig 2). Potting effort distribution in areas with low
212 confidence (26.7%) were excluded from the analysis.

213

214 **2.4. Habitat distribution**

215 A broadscale habitat map (European Nature Information System (EUNIS) level 3, 1m
216 resolution, overall accuracy 80%) was available for the Coquet to St Mary's Marine
217 Conservation Zone (CQSM MCZ) (Fig 3, C). Three broadscale habitat types were
218 identified (Fig 3, C): 'Atlantic and Mediterranean moderate energy circalittoral' (A4.2)

219 hereafter referred to as rock habitat, 'Sublittoral sand' (A5.2) hereafter referred to as
220 sand habitat, and 'Sublittoral mud' (A5.3) hereafter referred to as mud habitat. Full
221 descriptions of habitats and species assemblages are available from the EUNIS
222 website (<http://eunis.eea.europa.eu>).

223 **2.5. Data analysis**

224 All analyses were conducted in R (R Core Team, 2013). Temporal changes in
225 number of pots fished per month were analysed using a negative binomial model
226 with number of active vessels as a covariate. In order to account for seasonality, a
227 harmonic function was included but these covariates were non-significant and it was
228 deemed that monthly active vessel number encapsulated seasonality. Since total
229 numbers of pots deployed between 2006 and 2009 were estimated, three linear
230 models were run using low, mean and high estimates of pots fished by 10-12m
231 vessels (8.5, 14.3 and 20.1% respectively).

232 Spatio-temporal changes in Northumberland shellfishing effort were investigated by
233 comparing fishing effort values of randomly sampled locations (from fishing effort
234 distribution maps) between years (i.e. 2004–2005 vs 2006–2007, 2006–2007 vs
235 2008–2009, etc) using a permuted Monte Carlo simulation. Fishing effort distribution
236 maps were converted to raster format (pixel size 100x100m) each containing 88,604
237 unique pixels, of which 5000 were randomly sampled from each map. The fishing
238 effort values of sampled pixels were compared between years using a two-tailed
239 paired t-test permuted 50,000 times (Jackson and Somers, 1989). If greater than
240 95% of all permutations yielded significantly different results, it was deemed that the
241 compared maps differed. The number of statistically significant t-tests, mean t-values
242 and p-values from the permuted t-tests were calculated. All fishing effort maps were
243 tested against each other using this method. In order to visualise change across all
244 years, absolute change thematic maps were created using all fishing effort

245 distribution maps (Remmel, 2009). These highlight pixels where values change over
246 time.

247 Compositional analysis (Aebischer *et al.*, 1993) of fishers' habitat use was
248 undertaken by investigating the relationship between observed and expected potting
249 use of each habitat category in the CQSM MCZ, assuming that habitat use is
250 proportional to availability. This used 500 randomisation tests for annual groupings of
251 potting vessel sightings conducted in the *adehabitatHS* R package (Calenge, 2006).
252 The significance of habitat selection was tested using Wilk's lambda and a ranking
253 matrix constructed. The ranking matrix indicated whether the habitat type was used
254 significantly more or less than expected for each yearly fishing vessel sightings
255 value, and ranking of habitat selection by fishing vessels and year in order of
256 preference was displayed (Calenge, 2006). Although fishers target habitats outside
257 the CQSM MCZ, habitat data for these areas were not available. Therefore for this
258 analysis the CQSM MCZ polygon outline was selected as fishing vessel home range
259 (second order habitat selection, Johnson (1980)).

260 In order to further explore differences in habitat use between years an eigenanalysis
261 of selection ratios was undertaken (Calenge and Dufour, 2006). This method uses an
262 additive linear partitioning of the White and Garrott statistic (White and Garrott, 1990)
263 to maximise the difference between habitat use and availability on the first factorial
264 axis (Calenge and Dufour, 2006).

265 **3. Results**

266 ***3.1. Temporal changes in fishing effort***

267 NIFCA district pot-fishing permit (i.e. the number of fishing vessels which have a
268 licence to fish in the NIFCA district), decreased in number steadily from 2001 (155
269 permits) to 2011 (107 permits), there was then a small increase to 114-119 permits
270 between 2012 and 2014, and since 2014 the number of permits has remained

271 constant (Table 3). A similar trend was observed for the number of active vessels per
272 year, although not all vessels with permits were active; ~70-80% of permit holders
273 operating in any one year (except 2010 when only 43% of vessels with permits were
274 active) (Table 3). The proportion of the active <10m fishing vessels increased to
275 2011 (86%) before decreasing slightly from 2012-2014 (Table 3). The median
276 number of pots deployed per vessel per month doubled from 2001 to 2014 (Table 3).
277 The total number of pots fished in the district per year also showed a general
278 increase over time from 2001 to 2014 (Table 3).

279 Fishing effort per month declined between 2001 and 2007, increased between 2008
280 and 2010, and increased substantially from 2010 to 2014 (Fig 4). This trend was best
281 explained by a model with covariates: time (z-value = 17.4, $p < 0.0001$, where each
282 additional month predicted an increase of 1.01 pots fished), and number of active
283 vessels per month (z-value = 18.3, $p < 0.0001$, where each additional fishing vessel
284 accounted for a monthly increase of 1.1 pots fished) (Fig 4). The linear model run
285 using both low and high estimates of pots for vessels 10-12m (8.5 and 20.1% of pots
286 fished, respectively) did not change the overall trend with time (months) and the
287 number of active vessels significant (see supplementary materials).

288

289 ***3.2. Spatial-temporal changes in fishing effort***

290 Fishing effort distribution differed between all years (all years, $p < 0.001$). Fishing
291 effort decreased over large areas between 2004-2005 and 2006-2007 (Fig 5, t-value
292 = 36.1, $p < 0.001$), but increased in many areas between 2006 and 2013 (Fig 5, all t-
293 value < -19.2 , all $p < 0.001$). These changes were particularly close to the shore
294 (<2NM), with large increases in fishing effort between 2006 and 2013, although the
295 magnitude of differences between years was variable. Many areas further from shore

296 (>3NM) had decreasing fishing effort and increasing area with no fishing effort,
297 particularly between 2010 and (Fig 5).

298 Cumulative spatial changes across all years highlights these trends with either stable
299 or decreasing fishing effort further from shore, with most inshore areas increasing in
300 fishing effort (Fig 6). The maximum increase in fishing effort is much larger than the
301 maximum decrease in fishing effort: increases of up to 1150 pots.km⁻².year⁻¹
302 compared to decreases of 450 pots.km⁻².year⁻¹ (Fig 6).

303 **3.3. Fishers' habitat use over time**

304 At a broadscale habitat level, potting vessel sightings differed among substrate types
305 in all years ($\Lambda = 0.0152$; p-value = 0.004). Vessels showed a significant
306 preference for rock habitat (A4.2) over both sand (A5.2) and mud habitats (A5.3) (p-
307 value <0.05). Fishing vessels in most years tended to target sand (A5.2) over mud
308 (A5.3) habitats, although these differences were not significant. The eigenanalysis
309 showed all year groups following a similar pattern with a strong selection for rock
310 over other substrates (Fig 7).

311

312 **3.4. Changes in habitat potting pressure**

313 Potting pressure (pots.km⁻².year⁻¹) in the NIFCA district increased over the period
314 2004-2013 (Fig 5), especially in areas close to shore such as the CQSM MCZ.
315 Unfished areas in the CQSM decreased in extent over time (Fig 5). Across all years
316 the highest fishing pressures were on rock habitats (A4.2), sand habitats (A5.2) were
317 moderately fished and mud habitats (A5.3) were the least fished (Table 4,
318 supplementary materials). Potting pressure more than doubled on each habitat
319 between 2004 and 2013 (Table 4, supplementary materials) but the proportion of
320 total pots deployed on each habitat has remained constant, with only slight increases
321 or decreases between years (Table 4, supplementary materials). Between 2004 and

322 2013 fishers consistently targeted the same habitats each year, but increasing
323 potting effort.

324 **4. Discussion**

325 This study demonstrates the potential of existing datasets, collected through routine
326 fisheries patrols (Breen *et al.*, 2014; Turner *et al.*, 2015), to investigate temporal and
327 spatial changes in fishing effort. This may offer a viable alternative to VMS for
328 monitoring smaller vessel inshore fisheries (Breen *et al.*, 2014), particularly for static
329 gear fisheries because fishing vessel sightings provide strong confidence of
330 association with actual fishing activity. In addition, fishing effort distribution combined
331 with habitat data provide an insight into habitat selection, albeit at a broad scale in
332 this study. These fisheries–habitat interactions are the first step towards spatially
333 relevant habitat vulnerability assessments; data which are required for EBFM but
334 which is often lacking, particularly for the understudied inshore static gear fisheries.
335 The Northumberland shellfishery has been reported to have the highest vessel
336 sightings per unit effort in the UK (Vanstaen and Breen, 2014). This may make the
337 fishery particularly vulnerable to changes in legislation or area closures. The rich
338 data available make it well suited as a case study on the effects of area closures and
339 other types of management. However, in order to fully understand the implications of
340 fisheries spatial management, fisheries–habitat interactions must be understood.

341 **4.1. Temporal change in fishing effort**

342 Fishing effort (pots.month⁻¹) increased substantially in the study area between 2001
343 and 2014. Changes in fleet composition or fishers' behaviour may explain increases
344 in effort, although available information is largely anecdotal and further work is
345 recommended. The proportion of vessels <10m in the study area steadily increased
346 over time. These smaller vessels are not subject to as much legislation as vessels
347 >10m and have cheaper fishing licenses. Concurrently, increased uptake by local

348 fishers of improved fishing technology, including GPS and sonar, better vessel
349 layouts and hydraulic trap haulers, was reported (NIFCA, personal communication),
350 changes that would allow a greater number of pots per month to be fished and more
351 specific areas or habitats to be targeted, in-line with reports from other static-gear
352 fisheries (Acheson and Brewer, 2003; Brewer, 2010).

353 Non technological factors may also have contributed to the observed increase in
354 potting effort. Traditionally the Northumberland fishery has been a mixed and
355 seasonal fishery, with an array of species caught using different gears throughout the
356 year. For example, salmon (*Salmo salar*) was targeted using drift nets from June-
357 August; nephrops (*Nephrops norvegicus*) and white fish (e.g. cod, *Gadus morhua*)
358 using trawls in winter; and lobster and crab using pots in summer (NIFCA, personal
359 communication). However, declines in stocks of finfish and nephrops and the
360 increasing operational costs of maintaining and participating in these fisheries may
361 have resulted in many fishers solely fishing in the less regulated pot fishery targeting
362 high value lobster on a full time basis (Acheson and Brewer, 2003; Turner *et al.*,
363 2012; Molfese *et al.*, 2014). Although the number of active vessels in the district per
364 year has not increased (Table 3), fishers may be devoting more time to fishing
365 lobster full time and therefore increasing their effort.

366 Fishers may have increased effort in order to maintain levels of catch in the face of
367 decreasing abundance of target species (Pauly *et al.*, 2002). However direct
368 measure of the abundance of lobster and crab are impossible with current data.
369 Landings for both lobster and crab increased between 2001 and 2014 (NIFCA,
370 personal communication). However, calculating CPUE for trap fisheries is
371 problematic (Hilborn and Walters, 1992; Skerritt *et al.*, 2015) because the volume of
372 pots and frequency of hauling are often highly variable between fishermen and can
373 significantly alter CPUE estimates. Thus it remains unknown whether the increases

374 in pots in the fishery is due to declining landings, although this information may be
375 particularly useful for future studies.

376 **4.2. Spatio-temporal changes in fishing effort distribution**

377 Commercial fishing activities are often reported at very large scales (e.g. ICES
378 rectangles, approximately 30x60NM) (Brehme *et al.*, 2015). These data rarely
379 accurately reflect the heterogeneity of ocean activities (Parnell *et al.*, 2010; Brehme
380 *et al.*, 2015) and only allow the broadest of fishery-habitat interactions to be
381 examined. Knowledge of fine-scale fishing effort is important, particularly as a
382 prerequisite for the assessment and management of fisheries impacts on the
383 seabed; interactions with other industries or proposed MPAs (Crowder and Norse,
384 2008; Stewart *et al.*, 2010); and conflict reduction between competing marine sectors
385 (Katsanevakis *et al.*, 2011). Here, predictions of potting activities at a resolution of
386 1km² are made for the first time, these are of much finer resolution than previous
387 research, which has mapped fishing activities from 6 to 50km² (Breen *et al.*, 2014;
388 Brehme *et al.*, 2015). The more accurately activities can be mapped in these areas,
389 the greater the ability of policy makers to develop successful marine spatial plans
390 that minimise conflict (Dalton *et al.*, 2010).

391 This study demonstrates fishing effort increases, but these were not uniform across
392 the district over time. Activity became highly concentrated inshore; particularly in
393 2010-2011 and 2012-2013 (Fig 5). From a socio-economic perspective, potting may
394 therefore be more vulnerable to changes in legislation (e.g. limitations of pot
395 numbers, zonal management, fisheries exclusions) in the busy inshore marine
396 environment where competing demands exist between larger numbers of users and
397 where conflicts between different stakeholder groups occur (Dalton *et al.*, 2010).
398 Increased inshore fishing effort may be related to the increase in small boats within
399 the fleet which has been seen in a Greek fishery, where small <9m vessels' average

400 travel time to fishing locations was much lower than that of fishing vessels >15m
401 (Tzanatos *et al.*, 2006); smaller vessels being more likely to fish closer to shore than
402 larger vessels (FAO, 2005). Increasing fuel prices may also change behaviour, for
403 example there is evidence volatile fuel prices have led to fishing occurring closer to
404 port and reduced exploratory fishing in the UK (Abernethy *et al.*, 2010) although
405 further evidence is required to state this with confidence for Northumberland.

406 Although fishing distribution maps are increasingly proposed for marine spatial
407 management, temporal distribution of fishing effort has often been neglected
408 (Brehme *et al.*, 2015). This study highlights the high inter-annual variability of fishing
409 effort distribution over time at a regional scale and usefulness of monitoring fisheries
410 over long-time periods (Lynch, 2014). The lobster fishery in Maine has been shown
411 to change and evolve over time depending on fishers' responses to market forces
412 (Steneck *et al.*, 2011), informal rules amongst fishers (Acheson and Brewer, 2003;
413 Brewer, 2010), lobster population responses to changes in oceanographic conditions
414 (Steneck and Wilson, 2001; Incze *et al.*, 2006; Holland, 2011; Zhang *et al.*, 2011)
415 and to harvesting practices within the fishery (Acheson, 1988; Acheson and Brewer,
416 2003; Brewer, 2010). Fishers in the UK are likely to respond to similar drivers and
417 changes in fishing behaviour (Turner *et al.*, 2015) and therefore for accurate
418 management decisions, spatio-temporal patterns must also be understood. For
419 example, spatial-temporal dynamics of fishing have been shown to be important
420 when investigating effects of MPAs on fishing behaviour, where if patchy distributions
421 of concentrated effort densities through time are ignored, general overestimations of
422 fishing effort around no-take zones can occur (Stenzmuller *et al.*, 2008). In turn, this
423 could lead to an erroneous assessment of the fisheries benefits of the respective
424 MPAs (Stenzmuller *et al.*, 2008).

425 **4.3. Change in fishers' habitat use over time**

426 Results of temporal fisher-habitat interactions presented here had finer spatial
427 resolution than previous studies (Nilsson and Ziegler, 2007; Stelzenmüller *et al.*,
428 2008; Lambert *et al.*, 2011). A quantified estimate of fishers' historical use of an MCZ
429 was also provided; evidence which is often lacking during stakeholder engagement
430 process of designations (Caveen *et al.*, 2014). Fishers in the CQSM MCZ showed a
431 clear preference for rock habitats over sediment habitats in all years studied (2004–
432 2013). This assumes that the distribution and extent of habitats predicted from data
433 collected in 2014 are representative of the seabed throughout 2004-2013; but in this
434 moderate energy environment at circalittoral depths, major changes in the
435 distribution of substrata types are unlikely. Whether fishing grounds are chosen by
436 fishers' knowledge of habitat, target catch, or a combination of both, is unknown.
437 Based on historical knowledge and the widespread use of echo-sounder, fishers may
438 target broadscale habitat types. Habitat preference varied very little between 2004
439 and 2013 (Fig 7), albeit fishing pressure increased (Table 4). Infralittoral rock, which
440 is known to be fished in the CQSM MCZ, has not yet been included in the predictive
441 habitat maps used (Fitzsimmons *et al.* (2015) but is present within the CQSM MCZ.
442 As fishing pressure is high and increasing in the shallow inshore areas (Fig 5),
443 analysis of fisher-habitat interactions of these biodiverse areas is recommended for
444 any future management plans.

445 Analyses using broad habitat classification had high mapping accuracy (80%).
446 However, higher classification levels which include biological components (EUNIS
447 level 4-6), are particularly useful for locating and potential conservation of species of
448 interest and is often recommended in the literature in order to inform EBFM (Cogan
449 *et al.*, 2009; Caveen *et al.*, 2014). However, topographic, hydrographic and biological
450 homogeneity within the study site make creating maps with greater biological

451 resolution particularly problematic, resulting in relatively low accuracy (EUNIS level
452 5-6, 51% accuracy, Lightfoot *et al.*, unpublished). Investigation of fisheries-habitat
453 interactions using maps with high biological resolution holds great potential for wider
454 application, for example during designation or monitoring of fishers' use of MPAs,
455 particularly in areas of greater spatial heterogeneity where the prediction of biological
456 communities from acoustic data can be achieved with higher accuracy (Hill *et al.*,
457 2014; Sotheran *et al.*, 2014).

458 Incomplete knowledge of benthic assemblages and fishing gear–habitat interactions,
459 and uncertainties around resulting displacement of fishers from closed areas have
460 been obstacles to the successful implementation of MPAs (Caveen *et al.*, 2014). This
461 work has helped fill some of these knowledge gaps for the newly designated CQSM
462 MCZ. However, the information here is limited and maps predicting the distribution of
463 biological communities coupled with usage information are recommended, to allow
464 adaptive management for EBFM (Eno *et al.*, 2013). Fine-scale spatial assessments
465 will be particularly useful for prioritising protection of the most vulnerable or
466 biologically important habitats (Eno *et al.*, 2013). However, the impact of any
467 closures that this may require on fishers' distribution and fishing effort is not well
468 understood.

469 **5. Conclusion**

470 This study has demonstrated the potential for using fisheries enforcement data for
471 the monitoring of temporal and spatial fishing effort of static fishing gears in inshore
472 fisheries. Results of this research provide a crucial step towards a better
473 understanding of long term fishing effort and spatial distribution for Northumberland.
474 The analyses used here could be applied to other static fisheries and geographical
475 areas where fishers' sightings data have been collected (Breen *et al.*, 2014; Turner *et*
476 *al.*, 2015). The increase in effort and concentration of fishing activities over the study

477 period illustrates the importance of monitoring fishing distribution over appropriate
 478 time scales; data which are required for EBFM but which is often lacking (Campbell
 479 *et al.*, 2014), particularly for the understudied inshore fisheries. At a broadscale,
 480 fisheries-habitat interactions were investigated, however, further work using higher
 481 biological resolution maps are required for spatially relevant habitat vulnerability
 482 assessments. The decline in finfish stocks in parts of the UK and the US may have
 483 led to an increase in those participating in the pot fishery (Acheson and Brewer,
 484 2003; Turner, 2010; Molfese *et al.*, 2014). In light of the observed increase in effort,
 485 understanding the distribution, intensity and fisheries-habitat interactions of pot
 486 fishing is crucial in order to ensure sustainable shellfish stocks.

487

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 490 fishery, and for providing the fisheries landings and sightings data. We also thank
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 492 to Mark Shirley who helped with developing the map comparison methodology.

493

494 **Supplementary materials**

495 Results of temporal changes in number of pots fished per month using a negative
 496 binomial regression model with the lower estimate (8.5%) of pots fished for vessels
 497 10 -12 m between 2006 and 2009.

498 Regression coefficients, standard errors, t - value, and p-values significance for each
 499 variable using a negative binomial regression model with lower estimates for 2006 –
 500 2009 pots fished.

Estimate	Std Error	z - value	p- value
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Intercept	8.5	0.07	124.4	< 0.0001
Months	0.005	0.0002	17.91	< 0.0001
Active vessels	0.012	0.0006	19.62	< 0.0001

501

502 Results of temporal changes in number of pots fished per month using a negative
503 binomial regression model with the upper estimate (20.1%) of pots fished for vessels
504 10 -12 m between 2006 and 2009.

505 Regression coefficients, standard errors, t - value, and p-values significance for each
506 variable using a negative binomial regression model with higher estimates for 2006 –
507 2009 pots fished.

	Estimate	Std Error	z - value	p- value
Intercept	8.6	0.07	124.6	< 0.0001
Months	0.005	0.0003	16.15	< 0.0001
Active vessels	0.010	0.0007	16.1	< 0.0001

508

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776

777

778 **Tables**

779 Table 1. Shellfish vessel sightings and NIFCA patrol route data.

Year	Shellfish vessel Sightings	Standardised vessel sightings	NIFCA patrols	Patrol routes available (%)*
2004	1159	905	104	90 (87)
2005	771	578	99	47 (47)
2006	749	672	86	4 (4.7)
2007	515	478	86	49 (58)
2008	433	378	75	56 (75)
2009	529	509	71	45 (63)
2010	546	532	72	59 (81)
2011	539	451	101	79 (78.2)
2012	496	452	85	84 (98.8)
2013	479	431	83	71 (85.5)
2014	490	443	86	76 (88.4)

780 * The number of patrol routes (GIS shapefile) provided by NIFCA.

781

782 Table 2. Confidence classification used for the confidence assessment (modified
783 from Breen et *al.*, 2014).

Mean patrol effort for years 2004–2013	Confidence class
More than once in 2 weeks	High
Less than once in 2 weeks but more than once in 2 months	Moderate
Less than once in 2 months	Low

784

785

786 Table 3. Annual Northumberland potting fleet statistics (2001–2014) collated from
 787 NIFCA shellfisheries landings data. Not available (NA).

Year	Permits issued	Active Vessels (% active)	Active Vessels <10m (%)	Median pots month ⁻¹	Max pots worked month ⁻¹ *	Total pots worked year ⁻¹
2001	155	108 (70%)	52	250	32,624	257,450
2002	151	111 (74%)	54	250	33,087	250,030
2003	153	117 (76%)	57	250	31,121	242,391
2004	136	97 (71%)	60	270	28,620	233,642
2005	130	97 (75%)	60	300	31,433	246,085
2006	120	61 (51%)	NA	300	17,770	179,365
2007	NA	55	NA	300	24,140	179,538
2008	NA	61	NA	335	26,806	194,651
2009	NA	60	NA	360	29,326	221,687
2010	121	52 (43%)	82	400	24,341	186,740
2011	107	87 (81%)	86	430	43,252	345,086
2012	114	81 (71%)	85	450	42,666	332,471
2013	118	89 (84%)	84	400	39,934	354,193
2014	119	92 (77%)	80	500	41,044	388,575

788 * Total pots worked per month: sum of the maximum number of pots deployed per month by each vessel

789

790 Table 4. Mean potting pressure (pots.km⁻².year⁻¹) per habitat (EUNIS level 3) and
 791 proportion of pots deployed in the CQSM MCZ.

	2004 – 2005		2006 – 2007		2008 – 2009		2010 – 2011		2012 – 2013	
	Potting pressure	Proportion of pots	Potting pressure	Proportion of pots	Potting pressure	Proportion of pots	Potting pressure	Proportion of pots	Potting pressure	Proportion of pots
Rock	448.0	0.45	363.2	0.46	565.9	0.50	800.3	0.47	1117.4	0.48
Sand	377.4	0.31	286.8	0.29	414.2	0.29	642.4	0.30	898.5	0.31
Mud	319.5	0.24	275.7	0.25	327.9	0.21	521.8	0.22	649.8	0.21

792

793 **Figures legends**

794 Fig 1. Diagram of GIS processes undertaken to map distribution of potting effort
795 densities across the Northumberland IFCA district (modified from Spencer, 2013).
796 Raw data (black cylinders), GIS mapping procedures (grey boxes) and final potting
797 effort density distribution map (black dashed box) are shown.

798

799 Fig 2. Confidence data layer for the NIFCA district annual potting density map (2004-
800 2013).

801

802 Fig 3. Location of Northumberland in Great Britain (A). Location of the Coquet to St
803 Mary's MCZ within the NIFCA district (B). Broadscale habitat map (EUNIS Level 3,
804 for details on methodology see Fitzsimmons *et al.* (2015)) (C).

805

806 Fig 4. Monthly number of pots fished in the NIFCA district (2001–2014) with a line of
807 best fit (black line) and 95% confidence interval (grey polygon) modelled from the
808 regression coefficients obtained in the negative binomial regression analysis. The
809 number of pots deployed between 2006 and 2009 were estimated for vessels with
810 length 10-12m using mean estimates.

811

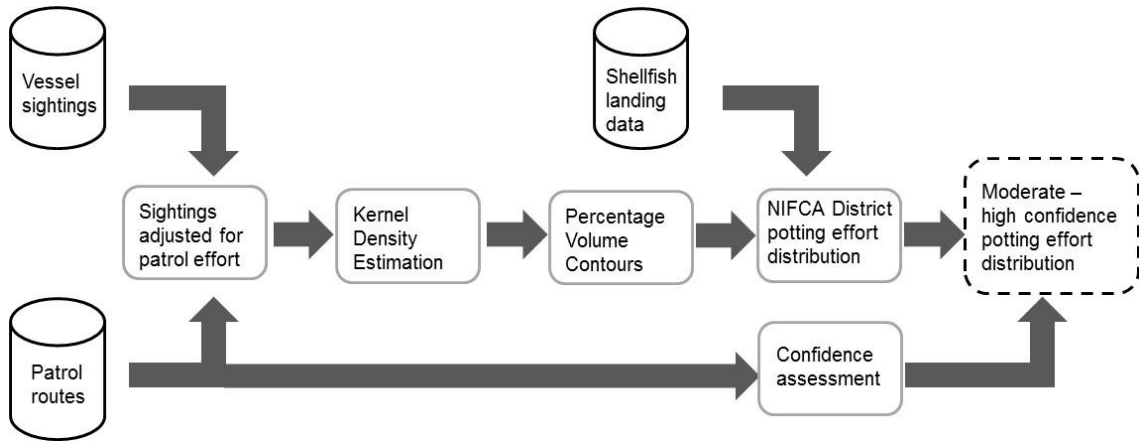
812 Fig 5. Distribution of fishing effort (pots.km⁻².year⁻¹) in areas with moderate – high
813 confidence for years: 2004-2005; 2006-2007; 2008-2009; 2010-2011; 2012-2013.

814

815 Fig 6. Changes in distribution of fishing effort (pots.km⁻².year⁻¹) in areas with
816 moderate - high confidence between 2004-2013.

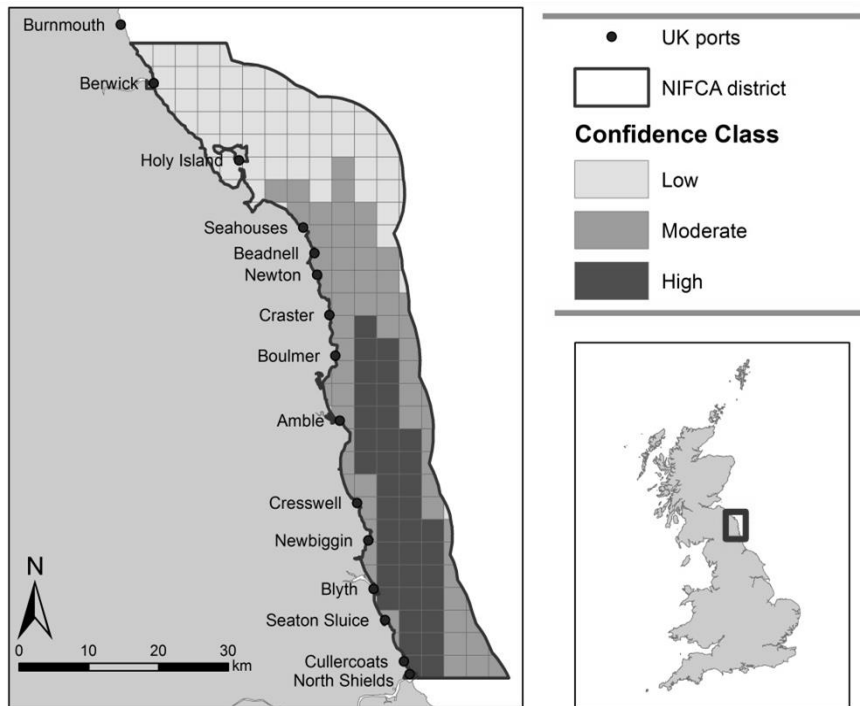
817 Fig 7. Results of the eigenanalysis of selection ratios for habitat selection by potting
818 vessels during 2004-2013 (labelled 1-10) on broadscale habitat variables.
819

820 **Figures**



821

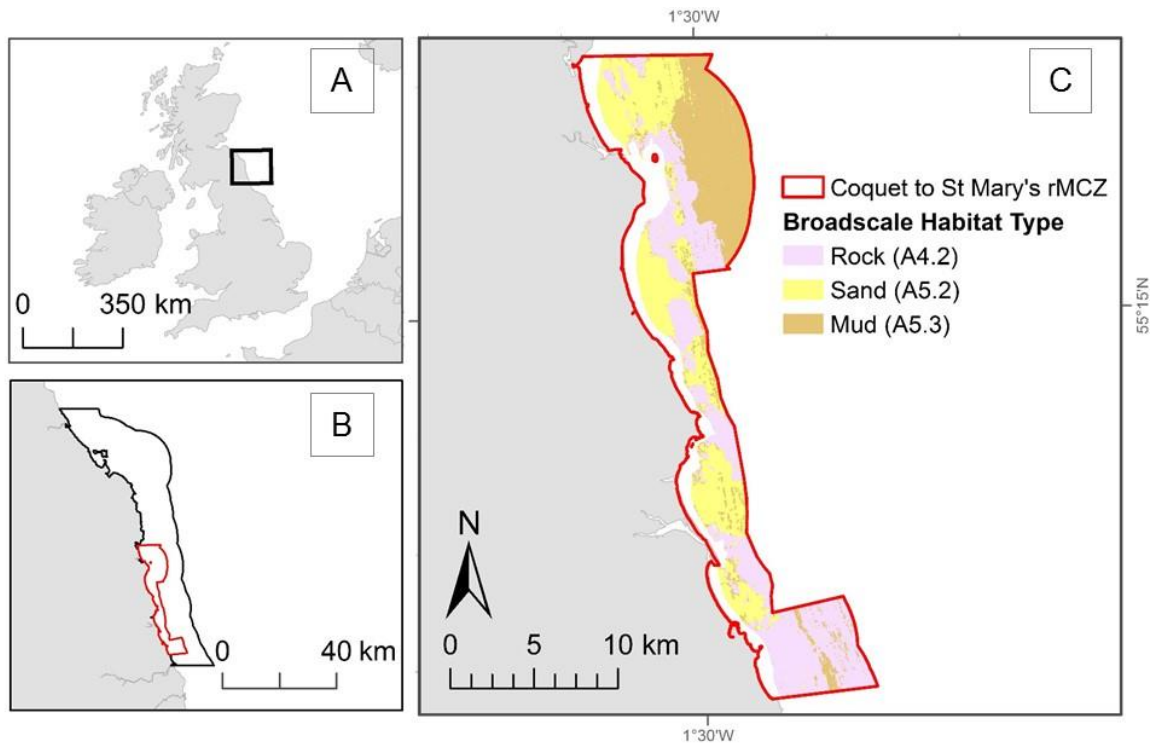
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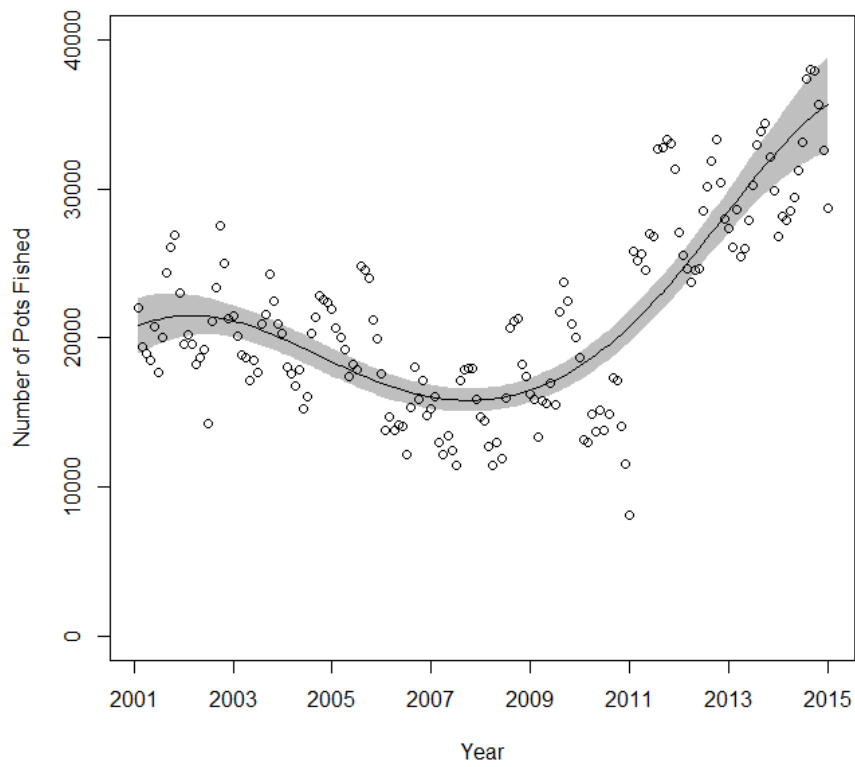
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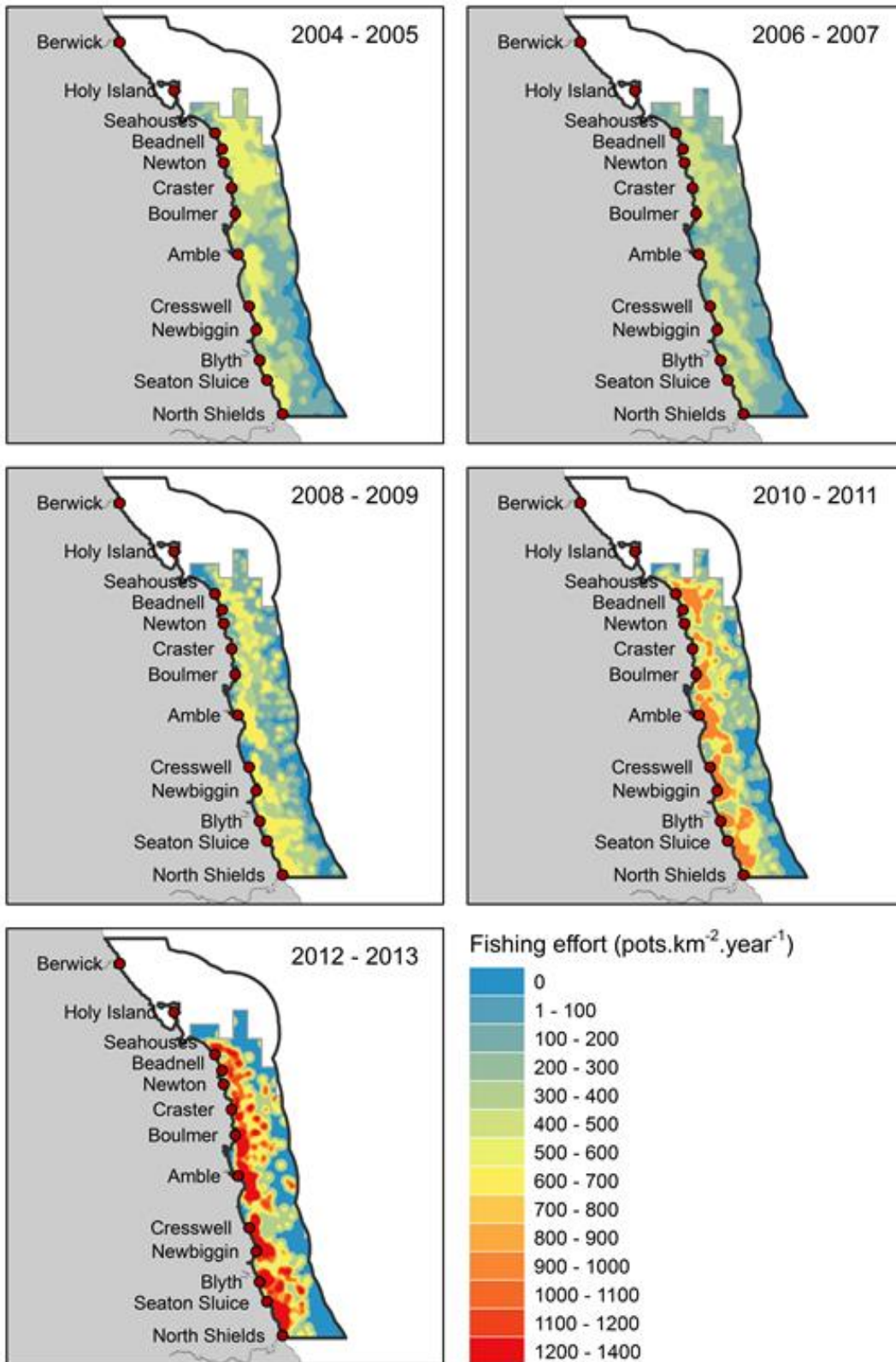
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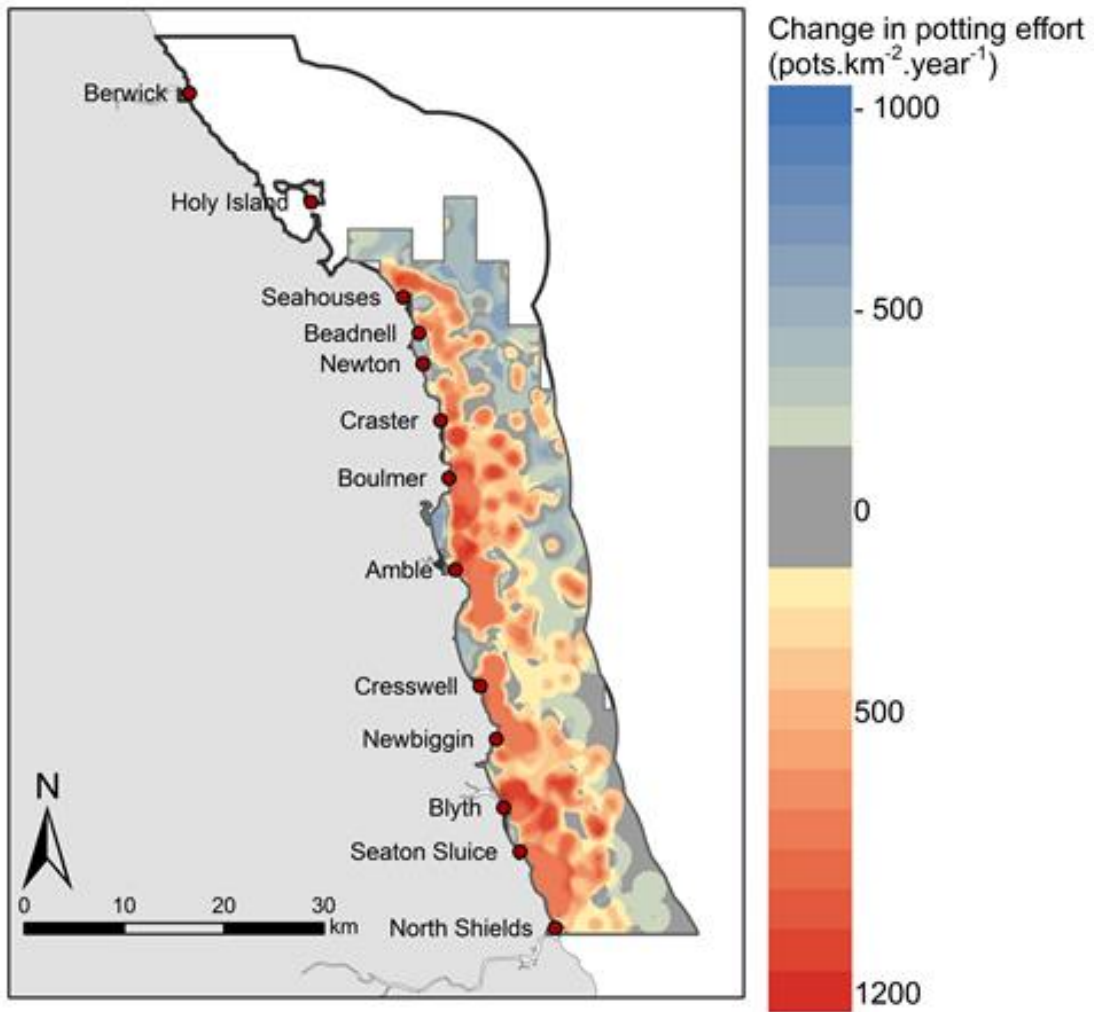
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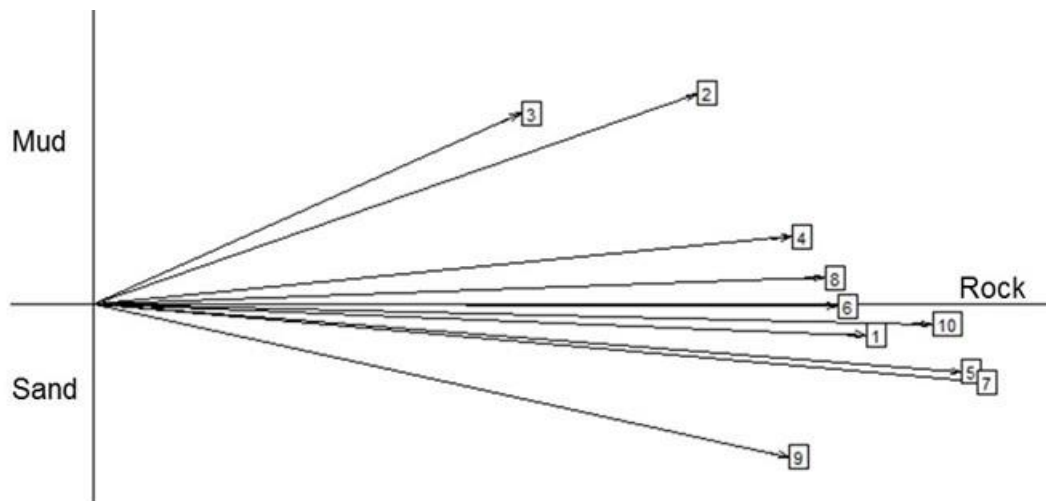


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