
Using rotation measure grids to detect cosmological magnetic fields: A Bayesian approach.


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Using rotation measure grids to detect cosmological magnetic fields: A Bayesian approach

V. Vacca\textsuperscript{1,2}, N. Oppermann\textsuperscript{3}, T. Enßlin\textsuperscript{2,4}, J. Jasche\textsuperscript{5,6}, M. Selig\textsuperscript{2,4,7}, M. Greiner\textsuperscript{2,4}, H. Junklewitz\textsuperscript{8}, M. Reinecke\textsuperscript{2}, M. Brüggen\textsuperscript{9}, E. Carretti\textsuperscript{10}, L. Feretti\textsuperscript{11}, C. Ferrari\textsuperscript{11}, C. A. Hales\textsuperscript{12,13}, C. Horellou\textsuperscript{14}, S. Ideguchi\textsuperscript{15}, M. Johnston-Hollitt\textsuperscript{16}, R. F. Pizzo\textsuperscript{17}, H. Röttgering\textsuperscript{18}, T. W. Shimwell\textsuperscript{18}, and K. Takahashi\textsuperscript{19}

1 INAF–Osservatorio Astronomico di Cagliari, via della Scienza 5, 09047 Selargius (CA), Italy
2 Max Planck Institute for Astrophysics, Karl-Schwarzschild-Str. 1, 85748 Garching, Germany
3 Canadian Institute for Theoretical Astrophysics, University of Toronto, 60 St. George Street, Toronto ON, M5S 3H8, Canada
4 Ludwig-Maximilians – Universität München, Geschwister-Scholl-Platz 1, 80539 München, Germany
5 CNRS, UMR 7095, Institut d’Astrophysique de Paris, 98 bis boulevard Arago, 75014 Paris, France
6 Excellence Cluster Universe, Boltzmannstr. 2, 85748 Garching, Germany
7 IBM Deutschland Research and Development GmbH Schönaicher Straße 220, 71032 Böblingen, Germany
8 Argelander-Institut für Astronomie, Auf dem Hügel 71, 52121 Bonn, Germany
9 Hamburger Sternwarte, University of Hamburg, Gojenbergsweg 112, 21029 Hamburg, Germany
10 INAF–Istituto di Radioastronomia, via Gobetti 101, 40129 Bologna, Italy
11 Laboratoire Lagrange, Université Côte d’Azur, Observatoire de la Côte d’Azur, CNRS, Boulevard de l’Observatoire, CS 34229, 06304 Nice Cedex 4, France
12 National Radio Astronomy Observatory, PO Box 0, Socorro, NM 87801, USA
13 Jansky Fellow of the National Radio Astronomy Observatory
14 Department of Earth and Space Sciences, Chalmers University of Technology, OSO, 439 92 Onsala, Sweden
15 Department of Physics, UNIST, 689-798 Ulsan, Korea
16 School of Chemical & Physical Sciences, Victoria University of Wellington, PO Box 600, 6014 Wellington, New Zealand
17 ASTRON, Postbus 2, 7990 AA Dwingeloo, The Netherlands
18 Leiden Observatory, Leiden University, PO Box 9513, 2300 RA Leiden, The Netherlands
19 Kumamoto University, 2-39-1, Kurokami, 860-8555 Kumamoto, Japan

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ABSTRACT

Determining magnetic field properties in different environments of the cosmic large-scale structure as well as their evolution over redshift is a fundamental step toward uncovering the origin of cosmic magnetic fields. Radio observations permit the study of extragalactic magnetic fields via measurements of the Faraday depth of extragalactic radio sources. Our aim is to investigate how much different extragalactic environments contribute to the Faraday depth variance of these sources. We develop a Bayesian algorithm to distinguish statistically Faraday depth variance contributions intrinsic to the source from those due to the medium between the source and the observer. In our algorithm the Galactic foreground and measurement noise are taken into account as the uncertainty correlations of the Galactic model. Additionally, our algorithm allows for the investigation of possible redshift evolution of the extragalactic contribution. This work presents the derivation of the algorithm and tests performed on mock observations. Because cosmic magnetism is one of the key science projects of the new generation of radio interferometers, we have predicted the performance of our algorithm on mock data collected with these instruments. According to our tests, high-quality catalogs of a few thousands of sources should already enable us to investigate magnetic fields in the cosmic structure.

Key words. methods: data analysis – methods: statistical – magnetic fields – polarization – large-scale structure of Universe

1. Introduction

The origin and evolution of cosmic magnetism are at present poorly understood. Answering the many open questions surrounding the physics of astrophysical magnetic fields is a difficult task since magnetic fields can be significantly affected by structure and galaxy formation and evolutionary processes. Their strength can be amplified, for example, in galaxy clusters through mergers and in galaxies through large-scale dynamos, invoking differential rotation and turbulence. Insights into the origin and properties of magnetic fields in the Universe could be provided by probing them on even larger scales. Along filaments and voids of the cosmic web, turbulent intracluster gas motions have not yet enhanced the magnetic field; its strength thus still depends on the seed field intensity, in contrast to galaxy clusters, where it probably mostly reflects the present level of turbulence (see, e.g., Donnert et al. 2009; Xu et al. 2010, 2011). Intervening magnetoionic media cause a difference in the phase velocity between the left-handed and right-handed circular polarization components of the linearly polarized synchrotron radiation emitted by a background radio source (e.g., Carilli & Taylor 2002; Govoni & Feretti 2004). This effect translates into a rotation of the intrinsic polarization angle, $\psi_0$.

$$\psi(\lambda^2) = \psi_0 + \phi \lambda^2.$$
Following Burn (1966), the observed polarization angle, $\psi$, depends on the observation wavelength, $\lambda$, through the Faraday depth, $\phi$:

$$\phi = a_0 \int_0^l B_i(z) n_e(z) \frac{dl}{dz},$$

(2)

where $a_0$ depends only on fundamental constants, $n_e$ is the electron density, $B_i$ is the component of the magnetic field along the line of sight, and $z_s$ is the redshift of the source. When the rotation is completely due to a foreground screen, the Faraday depth has the same value as the rotation measure (RM), defined by

$$\text{RM} = \frac{\partial \phi}{\partial l^2}.$$  

(3)

The Faraday depth is assumed to be positive when the line-of-sight average component of the magnetic field points toward the observer, otherwise it is negative for a field with an average component pointing away from the observer. The amount of Faraday depth measured by radio observations along a given line of sight is the sum of the contributions from the Milky Way, the emitting radio source, and any other source and large-scale structure in between. The investigation of these contributions and of their possible dependence on redshift is essential to discriminate among the different scenarios of magnetic field formation and evolution and, therefore, crucial for the understanding of cosmic magnetism. Sensitive observations, a good knowledge of the Galactic Faraday foreground screen, and a statistical approach that is able to properly combine all of the observational information are necessary. An all-sky map of the Galactic Faraday rotation foreground and an estimate of the overall extragalactic contribution has been derived by Oppermann et al. (2012, 2015) in the framework of “Information Field Theory” (Enßlin et al. 2009) by assuming a correlated Galactic foreground and a completely uncorrelated extragalactic term. In this paper, we propose a new, fully Bayesian approach aiming at further disentangling the contribution intrinsic to emitting sources from the contribution due to the intergalactic environment between the source and the observer and at investigating the dependence of these contributions on redshift.

The first direct proof of the existence of magnetic fields in large-scale extragalactic environments, i.e., galaxy clusters, dates back to the 1970s with the discovery of extended, diffuse, central synchrotron sources called radio halos (see, e.g., Feretti et al. 2012 for a review). Later, indirect evidence of the existence of intracluster magnetic fields has been given by several statistical studies on the effect of the Faraday rotation on the radio signal from background galaxies or galaxies embedded in galaxy clusters (Lavler & Dennison 1982; Vallée et al. 1986; Clarke et al. 2001; Johnston-Hollitt 2003; Clarke 2004; Johnston-Hollitt & Ekers 2004). On scales up to a few Mpc from the nearest galaxy cluster, possibly along filaments, only a few diffuse synchrotron sources have been reported (Harris et al. 1993; Bagchi et al. 2002; Kronberg et al. 2007; Giovannini et al. 2013, 2015). Magnetic fields with strengths on the order of $10^{-15} \text{ G}$ in voids might be indicated by $\gamma$-ray observations (see Neronov & Vovk 2010; Tavecchio et al. 2010; Takahashi et al. 2012, 2013; but see Broderick et al. 2014a,b for alternative possibilities). Nevertheless, up to now, a robust confirmed detection of magnetic fields on scales that are much larger than clusters is not available. Stassun et al. (2010) and Akahori et al. (2014a) investigated the possibility of statistically measuring Faraday rotation from intergalactic magnetic fields with present observations, showing that only the Square Kilometre Array (SKA) and its pathfinders are likely to succeed in this respect. By comparing the observations with single-scale magnetic field simulations, Pshirkov et al. (2015) infer an upper limit of $1.2 \text{ nG}$ for extragalactic large-scale magnetic fields, while the Planck Collaboration XIX (2016) derived a more stringent upper limit for primordial large-scale magnetic fields of $B < 0.67 \text{ nG}$ from the analysis of the Cosmic Microwave Background (CMB) power spectra and the effect on the ionization history (but see also Takahashi et al. 2005; Ichiki et al. 2006).

A number of authors examined a possible dependence of extragalactic Faraday depths on the redshift of the observed radio source, but no firm conclusion has yet been drawn. Kronberg & Perry (1982) found an increased variance of the Faraday depth in conjunction with higher redshifts, as also found in some later studies (e.g., Welter et al. 1984; Kronberg et al. 2008). However, Oren & Wolfe (1995) did not find any evidence of an increase of the variance of the Faraday depth as a function of the redshift, as also suggested by the recent work by Hammond et al. (2012) and Pshirkov et al. (2015).

The rest of this paper is organized as follows. In Sect. 2, we describe the theory behind our method. In Sect. 3, the tests performed are presented with predictions for the new generation of radio interferometers. Moreover, we outline a generalization of the algorithm in order to discriminate the contribution from different large-scale structures along the line of sight. Finally, in Sect. 4, we draw our conclusions. The application of the algorithm to real data is left for future work, as explained in the text. In the following, we adopt a $\Lambda$CDM cosmology with $H_0 = 67.3 \text{ km s}^{-1} \text{Mpc}^{-1}$, $\Omega_m = 0.315$, $\Omega_\Lambda = 0.685$, and $\Omega_k = 0.0$ (Planck Collaboration XVI 2014).

### 2. Theoretical framework

The probability for the extragalactic contribution, $\phi_e$, along the line of sight, $l$, to take on a value within the infinitesimal interval between $\phi_e$ and $\phi_e + d\phi_e$ given the data, $d$, and a model parameterization, $\Theta$, is given by the probability density distribution. As shown by Oppermann et al. (2015), the prior probability density distribution of the extragalactic Faraday depth can be approximated with a Gaussian. The mean and variance,

$$\langle \phi_e \rangle = \langle \phi_{e,j} | \phi_{i,e} \rangle \Theta,$$

(4)

$$\frac{\delta \phi^2}{\phi^2} = \langle (\phi_{e,j} - \langle \phi_{e,j} | \phi_{i,e} \rangle \Theta) (\phi_{e,j} - \langle \phi_{e,j} | \phi_{i,e} \rangle \Theta)^\dagger \rangle | \phi_{i,e} \rangle \Theta,$$

of this distribution are

$$\langle \phi_{e,j} \rangle = 0,$$

(5)

$$\langle \phi_{e,j}^2 \rangle = a_0^2 \int_0^\infty \int_0 \frac{dl}{dl'} \frac{dz}{dz'} \langle m(z) m(z') B_i(z) B_i(z') \rangle,$$

where these averages are calculated with respect to the prior of the extragalactic Faraday depth $P(\phi_{e,j} | \Theta)$. The zero mean results from the fact that we do not have any reason to suppose either a positive or a negative mean Faraday depth value. Frozen-in magnetic fields are expected to have strengths depending on redshift $z$. Because of the expansion of the Universe, lengths are stretched

$$\frac{I_0}{T} = (1 + z),$$

(6)

In an isotropically expanding Universe with no significant fluctuations, the mean electron density evolves as

$$\frac{\langle n_e \rangle}{\langle n_0 \rangle} = (1 + z)^3,$$

(7)
and, if the magnetic flux density is conserved, the magnetic field strength as
\[
\langle B \rangle / (B_0) = \left( \frac{n_e}{n_0} \right)^2 = (1 + z)^2,
\]
(8)
where \(n_0\), \((n_e)\), and \((B_0)\) are the present-day values, and \(l\), \((n_e)\), and \((B)\) are the values at the time when the signal was emitted by the source. If we consider these assumptions and we define a length scale \(\Lambda_l := \int df \langle B(l)B(l') / (B(l))^2 \rangle\), we obtain
\[
\langle \phi_{2e,c} \rangle \approx \alpha_0^2 \int_0^\chi (n_e^2) \langle B_0^2 \rangle \Lambda_0 (1 + z)^4 \frac{c}{H(z)} dz.
\]
(9)

For the derivation of this expression, see Appendix A. Here, we assumed an unstructured Universe and used the definition of proper displacement along a light ray, \(\frac{d}{c} = \frac{\Lambda_0}{1 + H_0 t}\). Moreover, we assumed that, within a correlation length \(\Lambda_0\), the redshift can be approximated to be constant. Magnetic field strength and structure and the electron density have different values in different environments, \(j\). In the following, we assume them to depend only on the environment and not on the location within an environment. This simplification renders the problem feasible. The letters \(i\) and \(j\) should not be mixed up since they have a different meaning. Indeed, they refer to the line of sight and to the environment (e.g., galaxy clusters, voids, filaments, and sheets), respectively.

In this paper, as a first step, we restrict our analysis to two components (scenario 2C): the emitting radio source itself, \(\chi\), and the medium between the source and our Galaxy, \(\sigma^2_{\text{env}}(\chi, \Theta)\), such that
\[
\langle \phi_{2e,c} \rangle = \sigma^2_{\text{env}}(\chi, \Theta) = \sigma^2_{\text{int}}(\chi, \Theta) + \sigma^2_{\text{env}}(\chi, \Theta).
\]
(10)

We denote with \(\Theta = [\sigma_{\text{int,0}}, \sigma_{\text{env,0}}, \chi_{\text{lim}}, \chi_{\text{red}}]\) an \(N\)-dimensional vector, where \(N\) is the number of parameters used in the representation of the Faraday depth variance. These are the parameters we want to infer: \(\sigma_{\text{int,0}}\) is the pure Faraday depth variance intrinsic to the emitting radio source, \(\sigma_{\text{env,0}}\) is the pure large-scale Faraday depth variance, \(\chi_{\text{lim}}\) describes the luminosity dependence of the intrinsic contribution, and \(\chi_{\text{red}}\) describes the redshift dependence of the large-scale contribution. We choose the following parameterization for the intrinsic contribution to the variance in Faraday depth,
\[
\sigma^2_{\text{int}}(\chi, \Theta) = \left( \frac{L_i}{L_0} \right)^{\chi_{\text{lim}}} \frac{\sigma_{\text{int,0}}}{(1 + z)^4},
\]
(11)
where \(L_i\) is the total luminosity of the source \(i\), \(L_0 = 10^{27}\) W/Hz, and \(\chi_{\text{lim}}\) absorbs possible dependencies on the luminosity of the source since faint sources may not be detected. In a flux-limited catalog, only the brightest sources are detected in the distant Universe. This selection effect can bias the evaluation of the contribution intrinsic to the source, e.g., if the Faraday depth associated with bright sources differs from that in faint sources. We take this possible effect into account with \(\chi_{\text{lim}}\). Alternatively, a parameterization based on polarized luminosity would also be a reasonable choice. For the environmental contribution, we choose as a parameterization
\[
\sigma^2_{\text{env}}(\chi, \Theta) = \frac{D_i(\chi, \chi_{\text{red}})}{D_0} \sigma^2_{\text{env,0}},
\]
(12)
where \(D_0 = 1\) Gpc, and \(D_i(\chi, \chi_{\text{red}})\) is defined as
\[
D_i(\chi, \chi_{\text{red}}) = \int_0^\chi \frac{c}{H(z)} (1 + z)^{4+\chi_{\text{red}}} dz
\]
(13)
to capture the redshift scaling of Eq. (9). We derived this redshift dependence assuming an isotropically expanding Universe with no significant fluctuations. Possible deviations from this simplistic scenario are taken into account by the parameter \(\chi_{\text{red}}\). Since the length of the path covered by the signal in the source is not known for each source, we factored it in \(\sigma^2_{\text{env,0}}\) in Eq. (11). We note that \(\sigma_{\text{int,0}}\) and \(\sigma_{\text{env,0}}\) were assumed to be independent of the redshift. In Eq. (11) the only redshift dependence is absorbed by the factor \((1 + z)^{-4}\) that takes into account the effect of redshift on Faraday rotation (squared), while in Eq. (12) it is absorbed by \(D_i(\chi, \chi_{\text{red}})\), which is given in Eq. (13).

This parameterization describes the simplest scenario. For more complex scenarios that include three components, we refer to Appendix C, where we introduce an additional constant and latitude-dependent term. Moreover, galaxies along the line of sight between a source and the observer can be responsible for high Faraday depth values (e.g., Kronberg & Perry 1982; Welter et al. 1984; Kronberg et al. 2008; Bernet et al. 2012), indicating magnetic field strengths in these intervening galaxies of \((1.8 \pm 0.4) \mu G\) (Farnes et al. 2014a). The rotation of the polarization angle due to these sources adds to that associated with the large-scale structure and, therefore, should be taken into account in a proper modeling. Since the aim of this paper is to give a proof of concept, we leave this for future work.

### 2.1. Bayesian inference

To constrain the vector \(\Theta = [\sigma_{\text{int,0}}, \sigma_{\text{env,0}}, \chi_{\text{lim}}, \chi_{\text{red}}]\) on the basis of the data, \(d\), we propose a Bayesian approach. The posterior probability distribution, \(P(s|d)\), on a signal, \(s\), after a dataset, \(d\), is acquired, can be expressed with Bayes’ theorem,
\[
P(s|d) = \frac{P(d|s)P(s)}{P(d)}.
\]
(14)
The prior probability distribution, \(P(s)\), is modified by the data, \(d\), through the likelihood, \(P(d|s)\). The evidence, \(P(d)\), is a normalization factor, obtained by marginalizing the joint probability, \(P(d, s) = P(d|s)P(s)\), over all possible configurations of the signal, \(s\).

In this context, the data, \(d\), can be represented as a vector with elements \(d_i\), with \(i = 1, \ldots, N_{\text{los}}\), where \(N_{\text{los}}\) is the total number of lines of sight. Each measurement, \(d_i\), is the Faraday depth evaluated in the direction of the source, \(i\), and is the result of the sum of a Galactic and an extragalactic contribution, \(\phi_{E,i}\) and \(\phi_{E,j}\), and the noise, \(n_i\), of the measurement process, such that
\[
d_i = \phi_{E,i} + \phi_{E,j} + n_i.
\]
(15)

From the observed data, the Galactic foreground should be removed as well as possible to reveal the extragalactic contribution. However, any estimation of the Galactic foreground is based on the same data and is facing the separation problem for Galactic and extragalactic contributions. The only available
discriminant (so far) is the large angular correlation the Galactic contribution shows. This allows for a statistical separation and Galactic model construction. Such a model inevitably has uncertainties and correlations among such uncertainties, which have to be properly taken into account in a statistical search for extragalactic Faraday signals. To this end, Oppermann et al. (2012, 2015) developed a fully Bayesian approach to reconstruct the Galactic Faraday depth foreground and estimate the extragalactic contribution and the involved uncertainties using the Faraday depth catalogs available to date. Their posterior for the extragalactic contribution can be used to further disentangle the intrinsic and environmental contributions. Analyses by Oppermann et al. (2012, 2015) rely on the assumption that for the Galactic Faraday depth foreground and estimate the extragalactic contribution and the involved uncertainties using different lines of sight can be modeled as uncorrelated. All angular correlations of Faraday depth on scales down to the effective resolution of the catalog (=0.5°) are absorbed by the Galactic component in this model. A more complete modeling would require us to take possible correlations in the extragalactic component into account. Thus, our assumptions imply that the values derived with the proposed algorithm for the contributions of different environments to the Faraday depth dispersion are a lower limit.

We cannot follow the prescription described in Appendix D.2.3 of Oppermann et al. (2015) because our prior assumptions are too different from theirs. Instead, we resort to Gibbs sampling (Geman & Geman 1984; Wandelt et al. 2004). This approach relies on the fact that sampling from the conditional probability densities,

\[
P(\phi_e) = \prod_{i=1}^{N_{\text{los}}} G(\phi_{e,i}, \sigma_{e,i}^2),
\]

with a standard deviation, \( \sigma_e \approx 7 \, \text{rad m}^{-2} \), irrespective of the line of sight\(^3\). Here, on the other hand, we want to test whether the variance is different for each line of sight, depending on the redshift of the source, according to Eqs. (11) and (12). We note that in our approach the angular separation of sources is assumed to be large enough that the magnetic fields probed by different lines of sight can be modeled as uncorrelated. All angular correlations of Faraday depth on scales down to the effective resolution of the catalog (=0.5°) are absorbed by the Galactic component in this model. A more complete modeling would require us to take possible correlations in the extragalactic component into account. Thus, our assumptions imply that the values derived with the proposed algorithm for the contributions of different environments to the Faraday depth dispersion are a lower limit.

We cannot follow the prescription described in Appendix D.2.3 of Oppermann et al. (2015) because our prior assumptions are too different from theirs. Instead, we resort to Gibbs sampling (Geman & Geman 1984; Wandelt et al. 2004). This approach relies on the fact that sampling from the conditional probability densities,

\[
\phi_e \leftarrow P(\phi_e | \Theta, d),
\]

and,

\[
\Theta \leftarrow P(\Theta | \phi_e, d),
\]

in a two-step iterative process is equivalent to draw samples from the joint probability density

\[
\phi_e, \Theta \leftarrow P(\Theta, \phi_e | d),
\]

if the process is ergodic.

For the parameters \( \sigma_{\text{int},0} \) and \( \sigma_{\text{env},0} \) we choose a uniform prior,

\[
P(\sigma_{\text{int},0}, \sigma_{\text{env},0}) \propto \text{const}.
\]

Results with other priors are discussed in Appendix D. Conversely, we do not expect the parameters \(\chi_{\text{lum}}\) and \(\chi_{\text{red}}\) to differ greatly from 0, since we have already accounted for all obvious redshift effects. This requirement is satisfied if we use the following Galactic priors

\[
P(\chi_{\text{lum}}, \chi_{\text{red}}) = G(\chi_{\text{lum}}, 1)G(\chi_{\text{red}}, 1),
\]

and in combination

\[
P(\Theta) = P(\sigma_{\text{int},0}, \sigma_{\text{env},0}) P(\chi_{\text{lum}}, \chi_{\text{red}}).
\]

Here, we describe the Gibbs sampling procedure mentioned in the previous section. We run the algorithm starting from values of the parameters \(\Theta\) randomly drawn from their prior. This \(\Theta\) vector is used to compute a variance for the prior of the extragalactic contribution,

\[
P(\phi_e | \Theta, d) = \prod_{i=1}^{N_{\text{los}}} G(\phi_{e,i}, \sigma_{e,i}^2(z_i, \Theta)),
\]

where \(\sigma_{e,i}^2(z_i, \Theta)\) is evaluated according to Eq. (10). A sample for the extragalactic contribution is drawn from the posterior

\[
P(\phi_e | \Theta, d) = \frac{P(d | \phi_e, \Theta) P(\phi_e | \Theta)}{P(d | \Theta)},
\]

following the approach described in Oppermann et al. (2015) with the Galactic power spectrum, Galactic profile, and correction factors to the observed noise variance (indicated by \(\eta\) in Oppermann et al. 2015) fixed to the published values. After fixing the extragalactic sample, a new \(\Theta\) sample is drawn from the conditional probability

\[
P(\Theta | \phi_e) = \frac{P(\Theta | \phi_e) P(\Theta)}{P(\phi_e)} \propto \prod_{i=1}^{N_{\text{los}}} G(\phi_{e,i}, \sigma_{e,i}^2(z_i, \Theta)) P(\Theta).
\]

Here, we drop the dependence on the data, \(d\), because \(\Theta\) and \(d\) are conditionally independent given \(\phi_e\). To sample from this distribution, we use a Metropolis-Hastings algorithm (Metropolis et al. 1953; Hastings 1970). When direct sampling is difficult, Metropolis-Hastings algorithms can approximate a probability distribution with random samples generated from the distribution itself. At each iteration a step in the parameter space is proposed according to a transition kernel and then accepted according to an acceptance function. If the proposed step is not accepted, the old \(\Theta\) values are kept and used to draw a new sample of the extragalactic Faraday depths.

The convergence criteria adopted in this work are described in Appendix B.

### 3. Results

In the following we present tests performed with different Faraday depth catalogs. These catalogs differ in the number of components used to generate the overall extragalactic Faraday depth, the numbers of lines of sight in the sky, and the observational uncertainties that are different for the different radio surveys considered here. In Sect. 3.1 we demonstrate that the algorithm is working properly for the two-component scenario described in Sect. 2. In Sect. 3.2, we present the prospects with the surveys planned with the new generation of radio interferometers: Low-Frequency Array (LOFAR), Australian Square Kilometre Array Pathfinder (ASKAP), and the SKA.

We perform tests assuming an overall extragalactic Faraday depth in agreement with the values presently inferred, namely \(\approx7.0 \, \text{rad m}^{-2}\) (Schnitzeler 2010; Oppermann et al. 2015), and comparable intrinsic and environmental contributions. To satisfy these two requirements, we need to use slightly different values of the \(\Theta\) parameters for surveys with different frequency specifications. Indeed, the contributions depend on the frequency through the luminosity of the source; see Eq. (11). Our choice of

\^3\ The notation \(G(x, X)\) indicates a one-dimensional Gaussian distribution for a variable \(x\) with zero mean and variance \(X\).
the Θ parameters translates to a strength of magnetic fields intrinsic to the source of

\[
\frac{(B_\Theta)S}{\mu G} \sim 0.5 \pm 1 \left( \frac{\langle n_0 \rangle}{10^{-3} \text{ cm}^{-3}} \right)^{-1} \left( \frac{\Lambda_0}{5 \text{ kpc}} \right)^{-1} \left( \frac{S}{100 \text{ kpc}} \right)^{-1},
\]

(26)

where \( S \) is the size of the emitting radio source, and to large-scale magnetic field strengths of

\[
\frac{(B_\Theta)_{\text{LLS}}}{nG} \sim 2 \left( \frac{\langle n_0 \rangle}{10^{-5} \text{ cm}^{-3}} \right)^{-1} \left( \frac{\Lambda_0}{5 \text{ Mpc}} \right)^{-1}.
\]

(27)

In the tests for LOFAR and SKA, we additionally consider an overall extragalactic Faraday rotation of \( \approx 0.7 \text{ rad m}^{-2} \) to mimic weaker fields. This corresponds to magnetic field values weaker by a factor ten than those given in Eqs. (26) and (27).

The two-component parameterization represents the simplest scenario. Nevertheless, the algorithm is also able to successfully deal with more complex scenarios that include a third constant or latitude-dependent component. These scenarios are discussed in Appendix C. Moreover, to assess whether different priors can have an impact on our results, we consider in Appendix D a flat prior in \( \sigma^2 \) and a flat prior in \( \ln(\sigma^2) \).

In Table 1, we give a summary of both a quantitative and a visual summary of the results of all of the tests we carried out. The posteriors for the most important tests are shown in the appendices.

### 3.1. Present instrument observations

We generate a mock catalog for the sample of sources used by Oppermann et al. (2012, 2015) to assess the quality of the algorithm. This mock catalog includes coordinates, redshifts, luminosities, and Faraday depth values.

The positions of the sources on the sky were kept the same as for the real sources. The majority (\( \approx 40,000 \)) belong to the catalog of Taylor et al. (2009) and, for 4003 of these sources, spectroscopic redshift measurements were published by Hammond et al. (2012). For most of the sources, these catalogs give a flux density measurement that allows us to compute the luminosity of the source. Where available, we use the measured redshift and flux density. For the vast majority of the sources we generate a mock redshift and, for a few of them, we generate a mock flux density value. Mock redshifts and flux densities are extracted independently from the two observed distributions. In Fig. 1, the distribution of both the real and mock sample of redshifts and flux densities is shown in the top and middle panel, respectively. In the bottom panel, the observed flux density versus redshift distribution is presented. These two quantities appear to be weakly correlated. For sake of simplicity, we neglected such correlation in our mock simulation, since it should not have any

\[
\approx 0.7 \text{ rad m}^{-2}.
\]

(26) For present observations this value represents the mean value of the observed uncertainties.

### References


### Table 1. Mock catalogs.

<table>
<thead>
<tr>
<th>Scenario</th>
<th>ID</th>
<th>Description</th>
<th>los #</th>
<th>( \sigma^2_{\text{noise}} ) (rad/m²)</th>
<th>Figure</th>
</tr>
</thead>
<tbody>
<tr>
<td>Two Component</td>
<td>2C1</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>41 632</td>
<td>13.0</td>
<td>2(a)</td>
</tr>
<tr>
<td></td>
<td>2C2</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>4003</td>
<td>13.0</td>
<td>2(b)</td>
</tr>
<tr>
<td></td>
<td>NP</td>
<td>LOFAR 120–160 MHz, North Polar Cap</td>
<td>2148</td>
<td>0.05</td>
<td>3(a,b)</td>
</tr>
<tr>
<td></td>
<td>GW</td>
<td>LOFAR 120–160 MHz, Great Wall</td>
<td>1036</td>
<td>0.05</td>
<td></td>
</tr>
<tr>
<td></td>
<td>POS</td>
<td>ASKAP-POSSUM 1130–1430 MHz, South Polar Cap</td>
<td>3476</td>
<td>6.0</td>
<td>5</td>
</tr>
<tr>
<td></td>
<td>B2SP1</td>
<td>SKA Band 2, 0.95–1.76 GHz, South Polar Cap</td>
<td>3476</td>
<td>2.0</td>
<td>4(a,b)</td>
</tr>
<tr>
<td></td>
<td>B2SP2</td>
<td>SKA Band 2, 0.95–1.76 GHz, South Polar Cap</td>
<td>1129</td>
<td>2.0</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B1SP1</td>
<td>SKA Band 1, 0.35–1.05 GHz, South Polar Cap</td>
<td>3476</td>
<td>0.3</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B1SP2</td>
<td>SKA Band 1, 0.35–1.05 GHz, South Polar Cap</td>
<td>1129</td>
<td>0.3</td>
<td></td>
</tr>
<tr>
<td>Three Component</td>
<td>C1</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>41 632</td>
<td>13.0</td>
<td>C.1(a)</td>
</tr>
<tr>
<td></td>
<td>C2</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>4003</td>
<td>13.0</td>
<td>C.1(b)</td>
</tr>
<tr>
<td>Latitude Dependence</td>
<td>LD1</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>41 632</td>
<td>13.0</td>
<td>C.2(a)</td>
</tr>
<tr>
<td></td>
<td>LD2</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>4003</td>
<td>13.0</td>
<td>C.2(b)</td>
</tr>
<tr>
<td>Prior 0</td>
<td>P0</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>41 632</td>
<td>13.0</td>
<td>D.1(a)</td>
</tr>
<tr>
<td>Prior 1</td>
<td>P1</td>
<td>Datasets used by Oppermann et al. (2012, 2015)</td>
<td>41 632</td>
<td>13.0</td>
<td>D.1(b)</td>
</tr>
</tbody>
</table>
Table 2. Quantitative summary of test results.

<table>
<thead>
<tr>
<th>ID</th>
<th>(\sigma_{\text{int,0}})</th>
<th>(\sigma_{\text{env,0}})</th>
<th>(\sigma_{c/\text{lat}})</th>
<th>(\chi_{\text{hum}})</th>
<th>(\chi_{\text{red}})</th>
<th>(\sigma_e)</th>
<th>((B_0)_S) (^\dagger)</th>
<th>((B_0)_S) (^\ddagger)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2C1</td>
<td>18.2</td>
<td>18.9 ± 0.8</td>
<td>1.4 ± 0.2</td>
<td>1.4 ± 0.2</td>
<td>0.3</td>
<td>1.0</td>
<td>0.99 ± 0.03</td>
<td>0.3</td>
</tr>
<tr>
<td>2C2</td>
<td>18.2</td>
<td>17.4 ± 1.4</td>
<td>0.6 ± 1.4</td>
<td>1.6 ± 0.4</td>
<td>0.5</td>
<td>1.0</td>
<td>1.1 ± 0.1</td>
<td>1.0</td>
</tr>
<tr>
<td>3C2</td>
<td>16.5</td>
<td>17.6 ± 1.0</td>
<td>1.1 ± 1.1</td>
<td>1.2 ± 0.2</td>
<td>0.5</td>
<td>2.4</td>
<td>0.9 ± 0.1</td>
<td>1.9</td>
</tr>
<tr>
<td>3C2</td>
<td>16.5</td>
<td>17.7 ± 1.9</td>
<td>0.6 ± 1.1</td>
<td>0.7 ± 0.3</td>
<td>1.3</td>
<td>3.9</td>
<td>0.9 ± 0.1</td>
<td>0.9</td>
</tr>
<tr>
<td>LD1</td>
<td>16.5</td>
<td>17.9 ± 0.9</td>
<td>1.5 ± 1.1</td>
<td>1.0 ± 0.2</td>
<td>0.3</td>
<td>0.58</td>
<td>0.9 ± 0.1</td>
<td>0.9</td>
</tr>
<tr>
<td>LD2</td>
<td>16.5</td>
<td>16.8 ± 1.5</td>
<td>0.2 ± 1.1</td>
<td>1.2 ± 0.4</td>
<td>0.3</td>
<td>0.58</td>
<td>0.4 ± 0.2</td>
<td>0.9</td>
</tr>
<tr>
<td>GW</td>
<td>8.6</td>
<td>9.5 ± 0.7</td>
<td>1.2 ± 1.4</td>
<td>1.0 ± 0.2</td>
<td>1.8</td>
<td>0.9</td>
<td>0.8 ± 0.1</td>
<td>1.1</td>
</tr>
<tr>
<td>NPa</td>
<td>8.6</td>
<td>7.4 ± 0.7</td>
<td>1.7 ± 1.4</td>
<td>1.6 ± 0.2</td>
<td>0.9</td>
<td>0.9</td>
<td>1.0 ± 0.1</td>
<td>1.4</td>
</tr>
<tr>
<td>POS</td>
<td>18.2</td>
<td>16.9 ± 1.8</td>
<td>0.8 ± 1.4</td>
<td>1.5 ± 0.3</td>
<td>0.4</td>
<td>1.0</td>
<td>1.0 ± 0.1</td>
<td>1.4</td>
</tr>
<tr>
<td>B2SP1a</td>
<td>18.2</td>
<td>18.5 ± 1.0</td>
<td>0.3 ± 1.4</td>
<td>1.4 ± 0.2</td>
<td>0.3</td>
<td>1.0</td>
<td>1.0 ± 0.05</td>
<td>0.3</td>
</tr>
<tr>
<td>B2SP2</td>
<td>18.2</td>
<td>19.9 ± 1.8</td>
<td>0.9 ± 1.4</td>
<td>1.2 ± 0.3</td>
<td>0.7</td>
<td>1.0</td>
<td>0.9 ± 0.1</td>
<td>1.1</td>
</tr>
<tr>
<td>B1SP1a</td>
<td>14.9</td>
<td>15.9 ± 0.7</td>
<td>1.5 ± 1.4</td>
<td>1.4 ± 0.2</td>
<td>0.3</td>
<td>1.0</td>
<td>0.98 ± 0.03</td>
<td>0.8</td>
</tr>
<tr>
<td>B1SP2</td>
<td>14.9</td>
<td>14.3 ± 1.9</td>
<td>0.3 ± 1.4</td>
<td>1.7 ± 0.4</td>
<td>0.7</td>
<td>1.0</td>
<td>1.0 ± 0.1</td>
<td>0.2</td>
</tr>
<tr>
<td>P0</td>
<td>18.2</td>
<td>18.3 ± 1.2</td>
<td>0.05 ± 1.4</td>
<td>1.6 ± 0.2</td>
<td>1.1</td>
<td>1.0</td>
<td>1.0 ± 0.04</td>
<td>0.2</td>
</tr>
<tr>
<td>P1</td>
<td>18.2</td>
<td>18.7 ± 1.0</td>
<td>0.4 ± 1.4</td>
<td>1.5 ± 0.2</td>
<td>0.9</td>
<td>1.0</td>
<td>1.0 ± 0.04</td>
<td>0.1</td>
</tr>
<tr>
<td>NPh</td>
<td>1.1</td>
<td>0.8 ± 0.2</td>
<td>1.4 ± 0.14</td>
<td>0.23 ± 0.05</td>
<td>1.9</td>
<td>0.9</td>
<td>1.1 ± 0.1</td>
<td>1.1</td>
</tr>
<tr>
<td>B2SP1b</td>
<td>1.7</td>
<td>2.6 ± 1.1</td>
<td>0.8 ± 0.11</td>
<td>0.13 ± 0.12</td>
<td>0.2</td>
<td>1.0</td>
<td>0.6 ± 0.2</td>
<td>1.9</td>
</tr>
<tr>
<td>B1SP1b</td>
<td>1.4</td>
<td>1.4 ± 0.2</td>
<td>0.2 ± 0.11</td>
<td>0.11 ± 0.04</td>
<td>0.05</td>
<td>1.0</td>
<td>0.9 ± 0.1</td>
<td>0.9</td>
</tr>
</tbody>
</table>

Notes. In Col. 1 the identification code (ID) of the catalog is denoted. In the remainder of the columns for each parameter the true value \(\tau\), the mean \(\mu\), the uncertainty \(\sigma\), and the displacement \(\epsilon\) (see Eq. (29)) between the mean and the true value in terms of uncertainty are given. In the last columns the standard deviation in the total extragalactic Faraday depth \(\sigma_e\), the average magnetic field intrinsic to the source \((B_0)_S\) and associated with the large-scale structure \((B_0)_S\) are reported.\(^\dagger\) For \((\rho_0) = 10^{-3} \text{ cm}^{-3}\), \(\Lambda_0 = 5 \text{ kpc}\), and \(S = 100 \text{ kpc}\), see Eq. (26).\(^\ddagger\) For \((\rho_0) = 10^{-5} \text{ cm}^{-3}\) and \(\Lambda_0 = 5 \text{ Mpc}\), see Eq. (27).
considered the Galactic contribution to be given by a sample extracted from the posterior of Oppermann et al. (2015). To mimic observational uncertainties, the noise variance has been computed for each source according to Eq. (37) in Oppermann et al. (2015), where as observed uncertainty, $\sigma_z$, we use the uncertainties reported in the observational catalogs and as $\eta_z$ we use the values recovered by Oppermann et al. (2015). The observational error of each measurement has been extracted from a Gaussian with this standard deviation and zero mean. Concerning the extragalactic contribution, in this test we consider the 2C scenario described in Sect. 2, namely an intrinsic and an environmental contribution,

$$\sigma^2_{\varphi, z, \Theta} = \left( \frac{L}{L_0} \right)^{\kappa_{\text{int}}} \sigma^2_{\text{int,0}} + \frac{D_i(z_i, \chi_{\text{red}})}{D_0} \sigma^2_{\text{env,0}}. \quad (28)$$

The variances in Eq. (28) depend on the redshifts and luminosities of the sources. Therefore, each source has a different variance. For each source, the extragalactic contribution is extracted from a Gaussian with this variance and zero mean. As summarized in Table 2, the contributions intrinsic to the source and due to the medium between the source and the observer are $\tau_{\text{int}} = 18.2 \text{ rad m}^{-2}$ and $\tau_{\text{env}} = 1.4 \text{ rad m}^{-2}$, respectively. Since the mean of the factor $L_i/L_0 (1 + z_i)^4$ is 0.06 and the mean of the factor $D_i/D_0$ is $\approx 15.5$, the standard deviation in the overall intrinsic and environmental components are $\sigma^2_{\text{int}} \approx 4.4 \text{ rad m}^{-2}$ and $\sigma^2_{\text{env}} \approx 5.3 \text{ rad m}^{-2}$. For this scenario, we run two tests corresponding to a different number of lines of sight:

- 41 632 (2C1). This is the total number of lines of sight for which an estimate of the extragalactic contribution is available from Oppermann et al. (2015);
- 4003 (2C2). This number accounts for all of the sources in the catalog 2C1 for which a redshift measurement is available as well (Hammond et al. 2012).

In Fig. 2, we show the results for tests 2C1 and 2C2, meaning with a two-component scenario for 41 632 lines of sight (a) and 4003 lines of sight (b), respectively. The histograms in the top plots of each column represent the one-dimensional projection of the posterior for the corresponding parameter. The dotted lines indicate the true value of the parameter. The dashed and dash-dotted lines describe the posterior statistics, namely the mean and the 1σ confidence level, respectively. The continuous lines indicate the prior used in our analysis. The panels in colors show the two-dimensional projection of the posterior for a given couple of parameters. These plots show that our algorithm is able to recover the mock $\theta$ values for this scenario. The inferred posterior mean values agree with the correct values within the uncertainties and the posterior distributions are much narrower than the prior distributions. The dispersion in the parameters $\Theta$ increases by decreasing the number of lines of sight, as expected. The plots indicate that some of the parameters are correlated, e.g., most noticeably $\sigma^2_{\text{env,0}} - \chi_{\text{red}}$, which show a strong anticorrelation. This feature can be understood in light of Eq. (12). Indeed, for a given Faraday rotation $\sigma_{\text{env}}$ associated with the structures between the source and the observer, larger $\sigma_{\text{env,0}}$ imply smaller $\chi_{\text{red}}$ and vice versa. We expect the correlation in the posterior to be significant for any reasonable parameterization that allows for the same number of degrees of freedom.

In order to have a compact and complete visualization, in the rest of the paper we present all of the tests we performed and their results as in Fig. 2.
Fig. 2. Results obtained with a two-component scenario for 41,632 (2C1) lines of sight in panel (a) and for 4,003 (2C2) in panel (b). In each panel the top plots of each column show the one-dimensional projection of the posterior and the true value (dotted line), the outcome of the analysis (dashed and dash-dotted lines), and the prior (continuous line). The panels in color show the two-dimensional marginalized views of the posterior as sampled.
3.2. Future prospects

We investigate the possibility to separate the Faraday rotation intrinsic to the emitting radio source from that due to the extragalactic environments between the source and the observer with the specifications of the SKA, its precursor, ASKAP, and its pathfinder, LOFAR. We generated the mock Faraday depth values for each source as described in Sect. 3.1. For each catalog, we extracted the noise contribution for each line of sight from a Gaussian with zero mean and standard deviation equal to maximum uncertainty in Faraday depth expected in the corresponding frequency range, according to Stepanov et al. (2008). Luminosities at frequencies different from 1.4 GHz were spectrally adjusted.

Since our approach assumes that all of the lines of sight are independent, i.e., sufficiently separated (≥1°) so that the cross-correlation function of their magnetic field is zero, in the following tests we compute the number of lines of sight considering a density of sources lower than or equal to one polarized source per square degree. The expected number density of sources for ASKAP and SKA per square degree is at least 100 times larger. Here, we investigate whether already with a small sample of lines of sight we would be able to put any constraints on the contribution from extragalactic large-scale environments, rather than exploit the information delivered by the full number of lines of sight and to show the full potential of ASKAP and SKA.

3.2.1. Low-Frequency Array

We only consider the LOFAR’s high band antennas (HBA) because the calibration of the low band antennas (LBA) is very challenging owing to the ionosphere. We select the HBA region of the spectrum with less contamination from radio frequency interference (120–160 MHz; Offringa et al. 2013). In this frequency range, the uncertainty on Faraday depth values is expected to be ≤0.05 rad m⁻² for a signal-to-noise ratio larger than 5 (Stepanov et al. 2008). Isophotic Faraday rotation can degrade the results at LOFAR frequencies; the same holds for SKA1 (band 1) observations; see the next section. Sotomayor-Beltrán et al. (2013) developed an approach to model isophotic Faraday rotations using LOFAR pulsar observations with precision up to 0.05–0.1 rad m⁻², comparable with the maximum uncertainty expected in this frequency band and considered here (see Table 1). According to Mulcahy et al. (2014), the expected number of polarized extragalactic radio sources is 1 per 1.7 square degrees for 8h-long observations, assuming an average degree of polarization of 1%, a spatial resolution of 20', and a detection threshold of 500 μJy/beam/rms⁵ that corresponds to \( S/N = 5 \).

On the basis of these assumptions we generate coordinates in the sky for a collection of sources corresponding to a survey (8h per pointing) in the direction of the north polar cap (NP). Among these sources we select those with Galactic latitude larger than 55°. This results in approximately 2200 sources. We derive a catalog assuming an overall extragalactic Faraday rotation \( \sigma_F \approx 7 \text{ rad m}^{-2} \) (NPb), and one assuming an overall extragalactic Faraday rotation \( \sigma_F \approx 0.7 \text{ rad m}^{-2} \) (NPb). The results are shown in Fig. 3, panels a and b. These plots show that LOFAR can provide good constraints for both values of the overall extragalactic Faraday depth if a few thousand of lines of sight are used with better performance for larger \( \sigma_F \). The posterior distributions are much narrower than the prior distributions and the posterior means agree with the correct values within 1–2σ. We also performed tests with a smaller number of lines of sight \( (N_{\text{los}} \approx 1000, \text{see Tables 1, 2, and Fig. 6}) \) still obtaining good performances even if, as expected, the posterior distributions were wider.

A survey of the sky at similar frequencies (170–200 MHz) but with lower spatial resolution (15.6') was conducted with the Murchison Widefield Array over an area of 2400 deg² (Bernardi et al. 2013). With a sensitivity in total intensity of 200 mJy/beam, the authors detected polarized emission only for one source among all of the sources brighter than 4 Jy, implying at these frequencies a fractional polarization below 2% for the remaining sources. The low number density derived by Bernardi et al. (2013) may be due to beam depolarization. The number of polarized sources in this frequency band is not yet clear and different assumptions on the density of sources translate to different predictions on the capabilities to infer properties of extragalactic magnetic fields.

We note that at frequencies ≥GHz the Galactic contribution can be described with a single Faraday screen along the line of sight (i.e., Uyaniker & Landecker 2002; Wolleben & Reich 2004). In the frequency band of LOFAR, the Galactic contribution can become more complex (e.g., Bernardi et al. 2009; Jelić et al. 2014; Zaroubi et al. 2015) with multiple, statistically significant Faraday depth peaks for several lines of sight. The tests performed here assume the simple scenario of a single-component Faraday depth spectrum. A more realistic treatment would require a more complex model for the Galactic foreground and is left for future work.

3.2.2. Square Kilometre Array

The SKA is expected to observe the entire Southern sky with a spatial resolution of 2" and a sensitivity in polarization of ≳4 μJy/beam (see, e.g., Johnston-Hollitt et al. 2015). The resulting sky grid of Faraday rotation values will be 200–300 times denser than the largest catalog currently available (see, e.g., Hales 2013). The better resolution of 2", compared to the 45" of Taylor et al. (2009), will make it possible to identify optical counterparts uniquely and, hence, to assign a redshift estimate to a larger number of sources through spectroscopic follow-up observations. The SKA1 Re-Baseline Design 2015 indicates the frequency bands 1, 2, and 5 as available on SKA_MID during SKA-Phase 1:

- band 1, 0.35–1.05 GHz;
- band 2, 0.95–1.76 GHz;
- band 5, 4.6–13.8 GHz.

In the following we consider the frequency range 0.95–1.76 GHz, since receivers in band 2 (B2SP1) should be constructed first.

We produce mock Faraday depth values assuming a maximum standard deviation in the noise distribution of the Faraday depth of 2.0 rad m⁻², according to Stepanov et al. (2008), for this frequency range and for \( S/N > 5 \). We generate a catalog of coordinates in the south polar cap (SP) based on the assumption of one polarized source per square degree and we select those with Galactic latitude \( b < -55° \). This translates in

4 For convenience, we use a single power-law \( F(\nu) \propto \nu^{-0.8} \), where \( F(\nu) \) is the flux density. We did not take into account any evolution of the radio source population (e.g., Condon et al. 2002; Mauch & Sadler 2007). This assumption does not affect our results. Indeed, the purpose of the work is to assess the capability of the algorithm to recover the θ parameters that describe the different extragalactic contributions, regardless of the assumption made to generate them.

5 Rmsf is the half-power width of the Faraday depth spread function.
Fig. 3. As Fig. 2 but for results obtained with a two-component scenario for LOFAR HBA observations for $N_{\text{los}} \approx 2200$ and an overall extragalactic standard deviation in Faraday depth of (a) $\approx 7 \, \text{rad m}^{-2}$ (NPa) and (b) $\approx 0.7 \, \text{rad m}^{-2}$ (NPb).
Fig. 4. As Fig. 2 but for results obtained with a two-component scenario for SKA observations in the frequency range 650–1670 MHz for $N_{\text{los}} \approx 3500$ and an overall extragalactic Faraday rotation of (a) $\approx 7.0 \text{ rad m}^{-2}$ (B2SP1a) and (b) $\approx 0.7 \text{ rad m}^{-2}$ (B2SP1b).
\( N_{\text{los}} \approx 3500 \). We refer to this catalog as B2SP1. We produce catalogs of Faraday depth values assuming \( \sigma_e \approx 7.0 \text{ rad m}^{-2} \) (B2SP1a) and \( \sigma_e \approx 0.7 \text{ rad m}^{-2} \) (B2SP1b).

In Fig. 4, we show the results for B2SP1a and B2SP1b, in panels a and b, respectively. The plots for \( \sigma_e \approx 7.0 \text{ rad m}^{-2} \) indicate that with \( N_{\text{los}} \approx 3500 \) we obtain a good disentangling of the environmental and intrinsic contributions and their redshift and luminosity dependence with narrow posterior distributions and mean values within \( \pm 1 \sigma \) from the true values. For the same amount of lines of sight but a smaller overall Faraday rotation \( \sigma_e \approx 0.7 \text{ rad m}^{-2} \), the dispersion in \( \sigma_{\text{mm},0}, \chi_{lum}, \text{ and } \chi_{\text{red}} \) becomes broader but with mean values still within a few standard deviations from the assumed value. On the other hand, we do not get good constraints for the parameter \( \sigma_{\text{env},0} \) that appears to be characterized by a large dispersion. The posterior distributions are much broader than those derived with LOFAR for the same overall extragalactic Faraday rotation (see Fig. 3). This is because of the different frequency range considered here. Indeed, despite the larger number of lines of sight included in this catalog, the maximum uncertainty in Faraday depth is larger by one order of magnitude, preventing the algorithm from constraining the parameters with high precision. In order to derive narrower posterior distributions, we would need to resort to a larger number of lines of sight or to a smaller observational uncertainty in Faraday depth. Since the sensitivity of the SKA will allow us to detect hundreds of sources per square degree, narrower posterior distribution of the parameters can be obtained by increasing the number of lines of sight.

For an overall extragalactic contribution \( \sigma_e \approx 7 \text{ rad m}^{-2} \), further tests with a smaller number of lines of sight (\( N_{\text{los}} \approx 1000 \)) show good performances, even if the posterior distributions are broader. In addition, for a direct comparison with LOFAR, we run tests for SKA observations in band 1 and obtain consistent results. All these tests are summarized in Table 2 and Fig. 6. In this paper, we do not consider the SKA frequency band 5. Even if by moving to a higher frequency sources have a higher degree of polarization, the maximum uncertainty in Faraday depth is larger and the total source counts is reduced. Consequently, we expect that the parameters are poorly constrained if the same number of lines of sight is taken.

The high spatial resolution of the polarization survey planned with SKA1, 2′, will permit us to resolve the large majority of the sources and, consequently, to image Faraday depth spatial variations on scales smaller than the source size. Therefore, we will be able to access the spatial correlation of the Faraday depth intrinsic to the source and of that due to the screen in front of it. The current version of the algorithm does not take into account any correlation of the magnetic field along different lines of sight. Therefore, its application to such a dense Faraday depth catalog would deliver a lower limit on the magnetic field strength, including only the uncorrelated component.

### 3.2.2. Australian Square Kilometre Array Pathfinder

The Polarisation Sky Survey of the Universe’s Magnetism (POSSUM: Gaensler et al. 2010) is planned between 1130 and 1430 MHz with ASKAP. The survey will reach a sensitivity in \( U \) and \( Q \) of \(<10 \mu \text{Jy/beam} \) and a resolution of 10′. This will result in a density of 70 polarized sources per square degree (Hales et al. 2014) and a Faraday depth catalog that is 100 times denser than those that currently exist (e.g., Taylor et al. 2009). To test the capabilities of this survey in constraining extragalactic magnetic fields, we use the same setup described in Sect. 3.2.2, but with an uncertainty drawn from a Gaussian with \( \sigma_{\text{noise}} = 6.0 \text{ rad m}^{-2} \). This should be a reliable approximation of the maximum uncertainty in Faraday depth for a polarized signal with \( S/N > 5 \) (Stepanov et al. 2008). The results are shown in Fig. 5. ASKAP observations already appear very promising for disentangling the contribution intrinsic to the source from that due to large-scale environments for \( \sigma_e \approx 7.0 \text{ rad m}^{-2} \); this is already the case if Faraday depth values are only available for one source per square degree. The dispersion in the parameters is larger than that derived in Sect. 3.2.2 for the same collection of sources and overall extragalactic Faraday variance (Fig. 4a), as expected as the maximum uncertainty in Faraday depth is larger. However, the mean values of the posterior agree with the true values within at most about \( 1 \sigma \).

### 3.3. Discussion

We developed a Bayesian algorithm to disentangle extragalactic contributions in the Faraday depth signal. This algorithm builds upon an algorithm to reconstruct the Galactic Faraday screen and its uncertainty-correlation structure previously presented by Oppermann et al. (2015). We tested the algorithm by modeling the overall extragalactic contribution as the sum of an intrinsic and an environmental component; as described in Sect. 3.1, but see Appendix C for the inclusion of a constant or a latitude-dependent term. These tests show that the algorithm is able to discriminate among the different components and their dependence on the luminosity and redshift of the source.

For test purposes, we built mock catalogs according to the specifications of the catalogs available in the literature after correcting for poorly known uncertainty information (see Sect. 3.1). The results in Fig. 2b indicate that by applying the algorithm to the currently available dataset, we could already infer preliminary information about extragalactic magnetic fields if a few thousand sources with reliable observational uncertainty were available. For the 4003 sources in Fig. 2b, indeed, redshift and flux density values are available. Nevertheless, since actually we do not consider all their Faraday depth noise variances to be reliable (see Appendix A of Oppermann et al. 2015) and the applied correction factors, \( \eta_i \), are only statistical estimates, we would need to sample in the \( \eta_i \)-parameter space as well to use the algorithm with real data, as described by Oppermann et al. (2015).

The modern techniques of analysis, such as model fitting of the fractional polarization components \( q \) and \( u \) (e.g., Farnsworth et al. 2011; Ideguchi et al. 2014), rotation measure synthesis (e.g., Brem
tjens & de Bruyn 2005; Akahori et al. 2014b) and Faraday synthesis (Bell & Enßlin 2012), and the future radio surveys will partially overcome this problem. The large bandwidth of the new radio interferometers will allow us to reduce the risk of \( \pi \)-ambiguity, which is particularly strong when the \( \chi^2 \)-fit approach is used, as well as to reach a sufficiently high resolution in Faraday depth to distinguish nearby Faraday components. We note that when the distance between two peaks in a Faraday spectrum is smaller than the resolution, the uncertainty in the Faraday depth may be driven by the Faraday point spread function (e.g., Farnsworth et al. 2011; Farnes et al. 2014b; Kumazaki et al. 2014). For these reasons, the catalogs coming from Faraday depth grids planned with LOFAR, ASKAP, and the SKA will be more reliable both in terms of Faraday depth values and uncertainties.

Therefore, we investigate the prospects of these simpler future datasets here and address the more complex application of our technique to present data in a separate work. We assumed the computation to be dominated by the uncertainties in the
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Fig. 5. As Fig. 2 but for results obtained with a two-component scenario for ASKAP observations in the frequency range 1130–1430 MHz for \( N_{\text{los}} \approx 3500 \) and an overall Faraday depth of \( \approx 7.0 \text{ rad m}^{-2} \) (POS).

Faraday depth estimates for each source, while the coordinates, luminosities, and redshifts to be exactly known. With the advent of highly-accurate Faraday depth catalogs, this may change and in future work we will need to investigate to what depths and accuracy redshifts, and luminosities are needed to apply the method we propose. This is particularly important for redshifts. Indeed, the catalog used in this work reports a spectroscopic redshift for each source (Hammond et al. 2012). Recently, optical surveys, such as 2MASS, WISE, and SuperCOSMOS have measured the photometric redshifts for millions of galaxies up to \( z \approx 0.5 \) (e.g., Bilicki et al. 2014), and the surveys planned with the next generation of telescopes will further increment this number. Nevertheless, photometric redshifts are less accurate than spectroscopic redshifts. This will require us to evaluate the impact of their uncertainties on our results.

Our tests indicate that LOFAR, ASKAP, and the SKA will allow us to infer information about cosmological magnetic fields already with a few thousands of lines of sight with better performance when lower frequencies are used. We want to stress that the uncertainties used in our tests only represent statistical uncertainties and any systematic issues have been neglected. In principle, LOFAR observations could already be used for this aim but the development of a pipeline for the reduction of polarization data is still in progress. The enhanced capabilities of the Jansky Very Large Array (JVLA) make the new centimeter-wavelength sky survey (VLASS\(^6\)) planned with this instrument a good opportunity for the application of this algorithm and for delivering significant results in the study of cosmic magnetism in the near future. Similarly, the frequency range (1–1.75 GHz), the angular resolution (13′′), the expected sensitivity (10 \( \mu \text{Jy/beam} \) over 300 MHz of bandwidth and 12 hours of observation), and the large field of view (8 square degrees) make the APERture Tile In Focus (APERTIF\(^7\)) a competitive instrument for the present investigation of cosmological magnetic fields.

In Table 2 we give a quantitative summary of the results. For each test we report the true values \( \tau \) of the \( \Theta \) parameters that describe the intrinsic and environmental contribution to the Faraday depth, their mean values \( \mu \), their uncertainties \( \sigma \), and the displacement of the mean from the true value in terms of the uncertainty,

\[
\epsilon = \left| \frac{\mu - \tau}{\sigma} \right|
\]

These values were computed after discarding the burn-in samples by visual inspection. The comparison of the results obtained with the mock catalogs created for present instruments 2C1 and 2C2 indicates that by increasing the number of sources with known redshift by a factor ten, the uncertainty in the \( \Theta \) parameters can be reduced by about a factor two. This would not longer be valid if the sources without redshift information represent a different population than the observed population, since in our test we adopted mock values for these sources randomly extracted from the observed redshift distribution. A similar result is obtained if the observational uncertainty \( \sigma_{\text{noise}} \) is reduced by approximately a factor ten, as shown by the comparison of results corresponding to catalog 2C2 and the SKA catalog B2SP1a.

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\(^6\) https://science.nrao.edu/science/surveys/vlass

\(^7\) https://www.astron.nl/general/apertif/apertif

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Fig. 6. Uncertainty on $\sigma_{\text{int,0}}, \sigma_{\text{env,0}}, \chi_{\text{lum}},$ and $\chi_{\text{red}}$ (from the top to the bottom) as a function of the observational uncertainty $\sigma_{\text{noise}}$ and the number of lines of sight $N_{\text{los}}$ for an overall extragalactic Faraday depth variance of $\approx 7.0 \text{ rad m}^{-2}$ (left panels) and $\approx 0.7 \text{ rad m}^{-2}$ (right panels). The size of the points is proportional to the uncertainty on the parameter. A description of this uncertainty is given also by the grayscale. Circles refer to scenarios including two components, while triangles refer to three-component scenarios. Continuous lines correspond to $\sigma_{\text{noise}}/N_{\text{los}} = \text{const.}$
These two tests refer to a similar number of lines of sight and to a similar mean frequency\(^8\). In Fig. 6 we present a visual summary of the results for all of the two- and three-component scenarios corresponding to an overall extragalactic Faraday rotation of approximately both 7 \(\text{rad m}^{-2}\) (left panels) and 0.7 \(\text{rad m}^{-2}\) (right panels) for the four parameters \(\sigma_{\text{in,0}}, \sigma_{\text{env,0}}, \chi_{\text{lum}}, \) and \(\chi_{\text{red}}\). The uncertainty on the parameters \(\Theta\) decreases by increasing the number of lines of sight, \(N_{\text{los}}\), and by decreasing the observational error, \(\sigma_{\text{noise}}\). The best results are obtained when a good compromise between these two numbers is used, as for example shown by the scenarios B1SP1\(a\) and B1SP1\(b\). Nevertheless, the comparison of the results of tests corresponding to different instruments can be not straightforward because they refer to different frequency bands and to slightly different values of the \(\Theta\) parameters.

The problem we are tackling is characterized by different complexities. We are looking for a very weak signal by using the residual information left in the data after the Galactic contribution is derived. At the same time, we expect this signal to be characterized by a possible redshift dependence, even if this dependence is very weak since it is not yet detected, and by cross-correlations of the extragalactic magnetic field along different lines of sight. In this work, we try to address the first two issues with a Bayesian approach that is able to combine all of the available observational information properly and allow for a redshift dependence in our model. On the one hand, we might overestimate the extragalactic contributions, since we are not including an uncorrelated Galactic component in the model. This term can be easily included in our algorithm, as shown by the tests in Appendix C and quantified with real data. On the other hand, we do not take into account a possible correlated component of the extragalactic magnetic field, which if present would be beneficial for our analysis. This means that the magnetic field values that can be inferred have to be considered rather as a lower limit, even if we expect this error to be small (e.g., Akahori & Ryu 2011). This is not a problem for surveys performed with LOFAR, since the expected density of extragalactic polarized sources is lower than one source per square degree. On the contrary, with ASKAP and the SKA, we will be able to detect at least 100 sources per square degree. An approach to deal with possible cross-correlations between lines of sight is being developed with the intention to apply this new technique to forthcoming ultradeep JVLA observations from the CHILES Con Pol survey (Hales et al., in prep.). The combination of the two methods would allow us to exploit in an optimal way the information coming from the denser grids of Faraday depth measurements provided by SKA and ASKAP surveys.

Finally, we stress that the aim of this paper is to give a proof of concept. Indeed, the present version of the algorithm requires a high computational burden that limits its efficiency. For example, the time required to run a test on our computer cluster is on the order of a couple of months per chain even when only a few thousands lines of sight are considered. We are currently working on performance optimization to make the algorithm suitable to be applied to the upcoming large Faraday depth catalogs.

### 3.4. Future developments

The work presented in this paper prepares a Bayesian technique to investigate magnetic fields in the large-scale structure, in particular, in filaments and voids. As a next step, we want to discriminate among the amount of Faraday rotation due to each large-scale structure environment (see also Vacca et al. 2015). When different large-scale environments are considered, the variance in the extragalactic Faraday rotation can be parameterized as

\[
(\phi_{\text{e},i,j}^2) \approx a_0^2 \int_0^Z \left( \frac{H(z)}{L_0} \right)^4 \sum_{i=1}^{N_{\text{env}}} l_i \sigma_{\text{lum},i}^2 \, \text{d}z, \tag{30}
\]

where \(\sigma_1, \sigma_2, \ldots, \sigma_{N_{\text{env}}}\) are the contributions from \(N_{\text{env}}\) different environments and \(l_i\) is the length of the line of sight, \(i\), through each environment, \(j\).

With a Bayesian approach, Jasche et al. (2010) (see also Leclercq et al. 2015) reconstructed the cosmic density field. They used optical data from the Sloan Digital Sky Survey (SDSS) Data Release 7 (Abazajian et al. 2009) and classified the structures as voids, sheets, filaments, and galaxy clusters, according to the classification scheme of Hahn et al. (2007). This reconstruction enables us to compute the path covered by the radio signal through each environment, i.e., the elements \(l_i\) in Eq. (30), once the position of the radio source is identified using the redshift. This posterior of the large-scale structure density field is available in the form of samples. Radio sources can belong to different environments (e.g., galaxy clusters and filaments) and the path covered by the signal in each environment differs for each radio source. These facts can be statistically taken into account with the use of a collection of sources distributed over all of the sky and of different realizations of the large-scale structure. We plan to use the full posterior of the large-scale structure to statistically estimate the amount of variance due to the different types of environments in the observed Faraday depths.

### 4. Conclusions

The properties of cosmic magnetic fields constitute outstanding questions in modern cosmology. To get a better understanding, it is essential to shed light on the properties of magnetic fields in large-scale environments, involving filaments and voids, where turbulent intracluster gas motions have not yet enhanced the magnetic field and, consequently, the magnetic field strength and structure still depend on the seed field power spectrum.

Upcoming generations of radio telescopes, first LOFAR, and in the next decades the SKA, will perform polarization sky surveys with high sensitivity. Modern techniques based on rotation measure synthesis and Faraday synthesis, will enable us to perform a proper analysis of the polarization properties of extragalactic radio sources, thus providing unprecedented, highly accurate Faraday depth catalogs in frequency ranges from a few hundreds MHz to a few GHz. A statistical approach is required to exploit the information encoded in these data. For this reason, we developed a Bayesian algorithm that is able to combine radio observations with luminosities and redshifts of sources, aiming at disentangling contributions to the extragalactic Faraday rotation intrinsic to radio sources and due to large-scale structures, and in this way infer information about large-scale magnetic fields. Knowledge of the redshift is essential in this approach. The present all-sky photometric optical surveys and the surveys planned with the next generation of telescopes will greatly enlarge the number of sources for which this information will be available.

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8 Indeed, the 2C2-sources all belong to the Taylor et al. (2009) catalog, therefore, their noise uncertainties refer to the frequency range 1365–1435 MHz.
The work described in this paper is a proof of concept and shows that our algorithm can be used to discriminate between the Faraday depth generated by the radio source itself and the contribution due to large-scale structures. Additionally, our algorithm is able to investigate the dependence of these terms on the redshift and radio luminosity of the sources. The tests performed showed that our algorithm can be used to discriminate between the correlated extragalactic magnetic field component, and of uncertainty in redshift. Nevertheless, we present a first step toward improvements, for example, computational efficiency, inclusion of a correlated extragalactic magnetic field component, and of uncertainty in redshift. Nevertheless, we present a first step toward a Bayesian study of large-scale magnetic fields associated with the cosmic large-scale structures.


References

Appendix A: Extragalactic Faraday depth variance

In this Appendix, we derive Eq. (9) from Eq. (5). In Eq. (5) we define the extragalactic Faraday depth variance

$$\langle \phi^2_{0c} \rangle \approx \frac{2}{\sigma^2_{0c}} \int_0^\infty \frac{dl'}{dz'} \int_0^\infty d\phi (n_e(z) n_e(z') B_l(z) B_l(z')) dz dz'. \quad (A.1)$$

This definition can also be expressed as a function of distance along the line of sight $l$

$$\langle \phi^2_{0c} \rangle \approx \frac{2}{\sigma^2_{0c}} \int_0^\infty \frac{dl}{dz} \int_0^{\sigma^2_{0c}-1} d\phi (n_e(l) B_l(l) B_l(l)). \quad (A.2)$$

If we assume that the thermal gas density is not characterized by significant fluctuations and define a new variable $r = l - l'$, we have

$$\langle n_e(l) n_e(l') B_l(l) B_l(l') \rangle \approx \langle n_e^2(l) \rangle \langle B_l(l) B_l(l') \rangle,$$

where the increment in wavelength due to the expansion of the universe reads

$$\Lambda = \int dr C_B(r n_e).$$

Recalling the definition of correlation length,

$$\Lambda_i = \int dr \frac{C_B(r n_e)}{(B^2_i)},$$

we obtain

$$\langle \phi^2_{0c} \rangle = \frac{2}{\sigma^2_{0c}} \int_0^\infty \frac{dl}{dz} \int_0^{\sigma^2_{0c}-1} d\phi \langle n_e^2(l) \rangle \Lambda_i \langle n_e \rangle (B^2_i). \quad (A.3)$$

As described in Sect. 2, in a homogeneous Universe $n_e = n_{e0}(1 + z)^2$, $\Lambda_i = \Lambda_{00}(1 + z)^{-1}$, and $B^2_i = (B^2_{00})(1 + z)^4$. Therefore,

$$\langle \phi^2_{0c} \rangle = \frac{2}{\sigma^2_{0c}} \int_0^\infty \frac{dl}{dz} \int_0^{\sigma^2_{0c}-1} d\phi \langle n_e \rangle (B^2_{00})^{-1} (1 + z)^4 dz,$$

where the increment in wavelength due to the expansion of the Universe has taken into account as well and we have assumed $z(l) \approx z(l + r)$. If we use the definition of proper displacement along a light ray $dl/dz = c(1 + z)^{-1}/H(z)$, this finally leads to Eq. (9),

$$\langle \phi^2_{0c} \rangle = \frac{2}{\sigma^2_{0c}} \int_0^\infty \frac{dl}{dz} \int_0^{\sigma^2_{0c}-1} d\phi \langle n_e \rangle (B^2_{00})^{-1} (1 + z)^4 dz. \quad (A.4)$$

In an inhomogeneous Universe with different environments, the differential variance in each environment is

$$\frac{d\phi^2_{R_{\Lambda}}(n_e)}{dx} = \langle n_e^2(z) \rangle (B^2_{00})^{-1} (1 + z)^4 dz. \quad (A.5)$$

Therefore, it follows

$$\langle \phi^2_{0c} \rangle = \frac{2}{\sigma^2_{0c}} \int_0^\infty \frac{dl}{dz} \int_0^{\sigma^2_{0c}-1} d\phi \langle n_e \rangle \frac{d\phi^2_{R_{\Lambda}}(n_e)}{dx}.$$

Appendix B: Convergence

We start the algorithm from two random positions in the $\Theta$ space and then explore the space\textsuperscript{9} until convergence. Each of these two sequences of steps in the $\Theta$ space is called Gibbs chain. To assess convergence of each Gibbs chain, we require the following conditions to be satisfied:

- the number of steps taken from each chain to be at least about $10 l_c$; for each parameter, $l_c$ is the number of steps at which the correlation coefficient $\rho_j$ drops to 10%;
- the Gelman and Rubin test (Gelman & Rubin 1992; Brooks & Gelman 1997). We evaluate the intrachain variance

$$I = \frac{1}{m} \sum_{j=1}^{m} s_j^2$$

and the interchain variance

$$B = \frac{n}{m - 1} \sum_{j=1}^{m} (\theta_j - \bar{\theta})^2$$

for our $\Theta$ parameters and use them to compute the potential scale reduction factor $R$ defined as

$$R = \sqrt{1 - \frac{B}{n I}},$$

where $m$ is the number of chains, $n$ is the half-length of each chain, $\theta_j$ and $s_j$ are the mean and the standard deviation of the $j$th chain, respectively, while $\theta$ is the mean of the chain means. We require $R = 1$ within a few percent for each parameter.

We consider the chains to be converged when both these conditions are satisfied.

As an example, in Fig. B.1 we show the plot of the potential scale reduction factor $R$ versus the number of steps for the $\Theta$ parameters in the scenario 2C1. The potential scale reduction factor

\textsuperscript{9} We tuned the variance of the Gaussian step proposal to ensure an acceptance rate of the Metropolis-Hastings algorithm of approximately 15–30%.

Fig. B.1. Potential scale reduction factor $R$ evaluated every ten samples for the parameters $\sigma_{\text{int},0}, \sigma_{\text{env},0}, \chi_{\text{lum}}$, and $\chi_{\text{red}}$, as a function of the number of steps in the MCMC, for the scenario 2C1. The continuous and dashed lines represent a potential scale reduction factor equal to 1.0 and 1.1, respectively. It can be seen that the Gelman and Rubin test indicates convergence after a few thousand steps.
has been evaluated every ten samples. After about 5000 steps we obtain $R = 1$ within a few percents. For each parameter of each test, we obtain $R$ within a few percents\(^ {10}\), which is sufficient to meet our convergence criteria. The aforementioned correlation coefficient $\rho_{ij}$ is calculated for each parameter $j$ as $\rho_{ij} = \frac{\sum_{k=1}^{n} (x_k - \theta_j)(x_{k+n} - \theta_j)}{\sqrt{\sum_{k=1}^{n} (x_k - \theta_j)^2 \sum_{k=1}^{n} (x_{k+n} - \theta_j)^2}}$.

where $k$ is the number of steps and $x_k$ is the value of one of these parameters for a given step. For all of the parameters in the scenario 2C1, $L_c$ turns out to be $\approx 3000$, while for the scenarios NPa and B2SP1a, the correlation length is about 500–1000. In these plots the steps in the burn-in phase have been discarded by visual inspection.

### Appendix C: Alternative scenarios

In this Appendix, we present the application to scenarios including three components, representing:

- an intrinsic, an environmental, and a constant contribution (scenario 3C),

$$\sigma_{c,\Theta}^2(z_i, \Theta) = \left( \frac{L_0}{L_0'} \right)^{\chi_{\text{int}}} \sigma_{\text{int},0}^2 + \frac{D(z_i, X_{\text{red}})}{D_0} \sigma_{\text{env},0}^2 + \sigma_{\text{int}}^2 \quad \text{(C.1)}$$

The constant contribution $\sigma_{c,\Theta}^2$ takes into account terms that are not described by the parameterization of the other two but that could nevertheless be present in our data (e.g., the ionosphere, under the assumption that this does not show any direction dependence);

- an intrinsic, an environmental, and a latitude-dependent contribution (scenario LD),

$$\sigma_{c,\Theta}^2(z_i, \Theta) = \left( \frac{L_0}{L_0'} \right)^{\chi_{\text{int}}} \sigma_{\text{int},0}^2 + \frac{D(z_i, X_{\text{red}})}{D_0} \sigma_{\text{env},0}^2 + p(b) \sigma_{\text{int}}^2 \quad \text{(C.2)}$$

where $p(b)$ is the Galactic profile from Oppermann et al. (2015). The latitude-dependent contribution $p(b)\sigma_{\text{int}}^2$ may explain a residual latitude dependence not taken into account in the modeling of Oppermann et al. (2015), e.g., an uncorrelated Galactic signal not captured by their analysis.

As for the simplest 2C-scenario, for each of these scenarios we run two tests corresponding to 41632 and 4003 lines of sight. Figures C.1 and C.2 show the results when a third constant component (tests 3C1 and 3C2) and latitude-dependent component (tests LD1 and LD2) are included. In both figures, we show the plots for 41632 lines of sight in panel a and for 4003 lines of sight in panel b.

\( ^{10} \) We mention a few exceptions: in two cases we get $R$ larger than 1 by 10%, in six cases by 20%, and in one case by 40%. We believe that these values would converge to 1 within a few percents by running the corresponding chains longer.

These plots indicate that the algorithm also performs well when three components are considered. As expected, the values of the $\Theta$ parameters recovered are less accurate when a lower number of lines of sight is used. The additional parameters tend to lead to a slight increase in the posterior uncertainty for the other parameters when comparing with the results of 2C1 and 2C2.

### Appendix D: Priors

In order to get a data-driven solution and to keep our assumptions as general as possible, an uninformative prior should be adopted for the $\Theta$ parameters. Since we included all of the main redshift and luminosity dependencies in our model, the Gaussian prior in Eq. (21) is suitable for $\chi_{\text{int}}$ and $\chi_{\text{red}}$. Concerning $\sigma_{\text{int},0}$ and $\sigma_{\text{env},0}$, we may ask if different priors can have an impact on our results. In Sect. 3.1, we adopted a flat prior,

$$P(\sigma) = \text{const.} \quad \text{(D.1)}$$

In this Appendix, we present two tests corresponding to extreme choices of these priors. Indeed, we considered a flat prior in $\sigma^2$ (scenario P1)

$$P(\sigma^2) = \text{const.} \quad \text{(D.2)}$$

and a flat prior in $\ln(\sigma^2)$ (scenario P0)

$$P(\ln(\sigma^2)) = \text{const.} \quad \text{(D.3)}$$

In Fig. D.1 we show the results for the two priors: flat in $\sigma^2$ in panel (a) and flat in $\ln(\sigma^2)$ in panel b.

The first choice is an optimistic prior, since it implies a suppression of $\sigma$ values $\ll 1$, pushing for the recovery of larger, possibly $\sim 1$ values of $\sigma$. The second choice is a pessimistic prior since it would weight all small and large $\sigma$ values in the same way, favoring negligible extragalactic contributions, easily compatible with the data because of the shape of the likelihood. We stress that the final results are not affected by the choice of the prior. However, this choice has an impact on the convergence time, since the starting point of each chain is randomly extracted from the prior. For example, for a flat prior in $\ln(\sigma^2)$, the chances to extract a very small $\sigma$ value ($\ll 1$) are larger than for the prior used in Sect. 3.1, possibly making the convergence time very long. For these tests, the number of lines of sight and the assumed noise properties are the same as in the 2C1 test.
Fig. C.1. As Fig. 2 but for results obtained with a three-component scenario, including a constant contribution, for 41,632 (3C1) lines of sight (a) and 4003 (3C2) lines of sight (b).
Fig. C.2. As Fig. 2 but for results obtained with a three-component scenario, including a latitude-dependent contribution for 41 632 (LD1) lines of sight a) and 4003 (LD2) lines of sight b).
Fig. D.1. As Fig. 2 but for results obtained with a two-component scenario and an overall extragalactic Faraday depth of \( \approx 7.0 \text{ rad m}^{-2} \) for (a) a flat prior in \( \sigma^2 \) (P1) and for (b) a flat prior in \( \ln(\sigma^2) \) (P0) for 41,632 lines of sight.